



SDAV Institute Final Report – February 2017

<http://sdav-scidac.org>

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1 Introduction

The purpose of the SDAV institute is to provide tools and expertise in scientific data management, analysis, and visualization to DOE’s application scientists. Our goal is to actively work with application teams to assist them in achieving breakthrough science, and to provide technical solutions in the data management, analysis, and visualization regimes that are broadly used by the computational science community. Over the last 5 years members of our institute worked directly with application scientists and DOE leadership-class facilities to assist them by applying the best tools and technologies at our disposal. We also enhanced our tools based on input from scientists on their needs. Many of the applications we

have been working with are based on connections with scientists established in previous years. However, we contacted additional scientists through our outreach activities, as well as engaging application teams running on leading DOE computing systems.

Our approach is to employ an evolutionary development and deployment process: first considering the application of existing tools, followed by the customization necessary for each particular application, and then the deployment in real frameworks and infrastructures. The institute is organized into three areas, each with area leaders, who keep track of progress, engagement of application scientists, and results. The areas are: (1) Data Management, (2) Data Analysis, and (3) Visualization. This report is organized along these areas. However, often there are multiple technologies from these areas that are applied to a single application need. These are described on a case-by-case basis in the appropriate sections. This final report for the SDAV Institute covers the 5-year period from February 2012 to February 2017.

This report covers activities in all SDAV institutions listed next. Laboratories: Argonne National Laboratory (ANL), Lawrence Berkeley National Laboratory (LBNL), Lawrence Livermore National Laboratory (LLNL), Los Alamos National Laboratory (LLNL), Oak Ridge National Laboratory (ORNL), Sandia National Laboratory (SNL). Universities: Georgia Institute of Technology, North Carolina State University, Northwestern University, Ohio State University, University of Oregon, Rutgers University, University of California at Davis, University of Utah. Industry: Kitware.

2 Executive Summary

This report is organized into sections and subsections, each covering an area of development and deployment of technologies applied to scientific applications of interest to the Department of Energy. Each sub-section includes: 1) a summary description of the research, development, and deployment carried out, the results and the extent to which the stated project objectives were met; 2) significant results, including major findings, developments, or conclusions; 3) products, such as publications and presentations, software developed, project website(s), technologies or techniques, inventions, awards, etc., and 4) conclusions of the projects and future directions for research, development, and deployment in this technology area.

The institute's web site, <http://www.sdav-scidac.org/>, contains in addition to publications, highlights, outreach and awards, the home pages for all the tools developed by members of the institutes and used by a variety of scientific applications. These home pages are extensive, and contain user guides, download instructions, and methods to communicate with developers and users. Rather than replicating this information in this report, we provide concise information on the problem areas each of the tools address, the approach for providing solutions to these problems, and the use of the tools by the scientific community.

We provide next a summary of key achievements, organized according to the structure of this report. We start with the Data Management area (section 3.1), followed by Data Analysis area (section 3.2), and ending with the Visualization area (section 3.3).

A key technology in the Data Management area is I/O frameworks (section 3.1.1). I/O can be a major bottleneck when running large scale computations (simulations, analysis, visualization) on large parallel machines. When each processor reads/writes data independently from other processors, this overwhelms the I/O system with too many concurrent I/O operations, resulting in poor utilization of I/O resources and thus long I/O times. I/O frameworks intercept I/O operations, keep the data in memory when possible, and thus isolate the I/O from computation. This allows computation to continue while the I/O framework can combine I/O from multiple nodes into larger I/O operations and schedule read/write operations independently of the computation. This approach has proven to achieve from 10 to 100 fold improvements using one of SDAV's I/O frameworks, called ADIOS. ADIOS has been used with a large variety of scientific applications, about 15 different simulation codes so far. Another approach is to exploit the topology of the system interconnect, thus reducing the cost of global synchronization. This

approach, taken by the GLEAN framework, showed multi-fold improvement over existing implementations. Another key technology for understanding the effect of I/O on the global efficiency of a running code is to monitor I/O operations with little interference. SDAV has been using such a tool, called Darshan, and improving it over the years to provide accurate I/O characterization. It is being used as a standard tool on all major DOE supercomputing facilities.

Another advantage of capturing I/O operations, is that this allows the data to stay in memory for a period of time, and therefore enable operations over the data before it is written out to disk. This is one method for enabling *in situ* processing. Several activities can take place while data is still in memory. One is enabling coupling of codes while data is still in memory while two or more codes are running concurrently on different node allocation on supercomputers. Such a tool is DataSpaces, which facilitates data exchange and transformation between codes while the data is still in memory. Another *in situ* activity provided by the FlexPath tool is scheduling and streaming data. Naturally, these tools can be embedded in an I/O framework, and indeed they were integrated into ADIOS. Other activities that can be performed *in situ* processing is in “on-the-fly” analysis while data is still being generated (e.g. the first few time steps of a simulation), visualizing data *in situ*, generating indexes *in situ*, etc. These techniques have shown to enable scientific computations and explorations that were previously impossible (see section 3.1.2).

An important challenge for scientists dealing with large volumes of data is to identify important structures and patterns in the data. For example, repeated searching for a pattern from trillions of particles in a plasma simulation or billions of particles in a cosmology simulation is prohibitive because each search can take many minutes. Indexing the data (a one-time cost) so that it may be searched multiple times is essential. The challenge is to have an indexing method that allows the index to be built quickly with a single run over the data, consume limited space to store, and enable very efficient searching for patterns of interest to our scientist partners. Such an index capability that runs in parallel over the data, called FastQuery, was developed by SDAV and has shown to be highly efficient (and provably optimal) for scientific data (section 3.1.3). As an example, it has been used to search over a trillion particles in 10 seconds for a magnetic reconnection application. Over the SDAV period it was enhanced to handle multiple popular file formats (including HDF5 and PnetCDF), was embedded into the ADIOS framework, and was extended to work with AMR data.

Another aspect of data indexing is to first compress the data (both lossy and lossless compression), and then develop effective indexing over the compressed data. Such tools, called ALACRITY and ISOBAR, are described in section 3.1.4, and shown to achieve compression as low as 55% of the original data, and having low space overhead for the index (less than 25% of original data), while achieving 28-35 fold search improvement over uncompressed indexes.

In section 3.1.5, we describe work in support of popular parallel I/O tools and file formats that serve a significant fraction of I/O requirements from DOE applications. In support of the HPC software stack, SDAV has maintained and improved the ROMIO MPI-IO implementation, which is available on every DOE supercomputing platform. The most impressive improvement was the redesign of the ROMIO internal data structures to reduce memory utilization in previously worst case scenarios to only 1.1% of its original size. Furthermore, working with IBM to tune the ROMIO algorithms, the performance improved by as much as 15 fold. In addition, one of the parallel file formats that uses MPI-IO internally, Parallel netCDF (PnetCDF), was developed by SDAV. It is an efficient parallel implementation of the classic netCDF format used by several scientific communities, most notably the climate research community. PnetCDF is available on all production DOE supercomputer facilities. SDAV also provides support for an innovative file structure, based on a hierarchical multi-resolution data format. The data format is referred to as z-ordering space filling method, which lends itself to extract the data at different resolutions with minimal overhead. The software, called PIDX, is available as a library, installed on all DOE supercomputing facilities, and provides fast querying at the desired resolution for data analytics and remote streaming. It has been shown to be able to stream data at a sustained data transfer rate equal to

80% of the nominal I/O bandwidth of the hardware, which is extremely important for visualization tools running remotely.

Data Analysis (Section 3.2) is the process of discovering interesting features and patterns in data. This process usually requires the transformation of the data in order to highlight the features of interest, including selection of subsets of the data based on features, summarization, statistical methods, representation of topological features, and tracking evolution of patterns over time and space. In SDAV, we have a collection of tools that use such techniques. Section 3.2.1 describes techniques for accelerating visual analysis and exploration. These include special data structures that provided nearly linear scaling of the calculation of distance fields (a technique to visually represent 2D and 3D isosurfaces). This technique has been used on up to 350 million triangles for astrophysics, climate, combustion, cosmology, and fusion applications. In addition, such techniques have been enhanced to run *in situ* in order to enable sophisticated volume feature exploration in large-scale data. Another visual exploration method is to track the trajectory of particles over time. Such a tool, running in parallel, called Ultravis-P, was developed and used since the beginning of SDAV. However, since it is often better to see the trajectory in the context of the spatial-temporal volume, a new trajectory-based flow feature tracking method was developed for joint particle/volume datasets. It was used for spatio-temporal particle track visualization of combustion and atmospheric datasets.

Another class of data analysis methods focus on identification and tracking of topological features in data (section 3.2.2). One such tool, called MSCEER, leverages Morse-Smale complexes to explore surface interactions of materials and was applied to multiple domains, including analysis of clean combustion and design of battery materials. Another topology-based tool was designed for the exploration high-dimensional spaces. The tool, called ND²AV, helps the visual and analytical exploration of problems that have a large number of parameters, as is common in many scientific areas. Recently, it has been applied to high energy density physics, and to nuclear reactor safety problems.

Flow field analysis and visualization techniques are described in section 3.2.3. They are used for a wide variety of spatio-temporal analysis tasks for a range of science applications. As the volume of data from simulations increases, it is essential that such techniques be accelerated by parallel computation methods. Such techniques were developed in SDAV, and have been shown to scale linearly. Furthermore, lower levels of precision can be processed in real time, and full precision can now be processed in the order of only 10 seconds for large scale datasets. Another activity for scalable stream surface computation was integrated into a library called OSUFlow, and was integrated into the VTK framework.

Related to flow field analysis is the ability to track the temporal history of features in space (section 3.2.4). A specialized tool, called TALASS, was designed to show the progression of particle tracks over time and was applied to many areas, including turbulent combustion research, astronomical simulations, weather analysis, and plasma physics. Another activity took the approach of controlling the execution of a plasma-based particle acceleration code (called WARP) from the VisIt tool, so that scientists can drive analysis *in situ*, while data is still in memory. This resulted in the ability, for the first time, of the scientists to observe in real-time the progression of the accelerator wake-field in 3D.

As data volumes increase, visual data exploration tools need to be improved to make best use of processing technologies. These activities are described in section 3.2. The two primary visualization frameworks, VisIt and ParaView, used by scientific communities well before SciDAC-3, needed to be enhanced to take advantage of multi-core and many-core architectures. Some of the enhancements could be made internally to each framework. However, it was the goal of SDAV to share a common framework for taking advantage of multi/many core architectures, reducing the long-term maintenance cost of these tools and ensuring new developments are available in both toolsets. This activity led to a remarkable achievement in the visualization area: a single framework, called VTK-m (see section 3.3.2), now provides multi/many core operators to the two main parallel visualization tools provided by the institute. This achievement required to cooperation of SDAV researchers from five DOE laboratories and Kitware

(which provides support for VTK) as well as NVIDIA, and the integration of three different projects with VTK. The three existing projects that were integrated into VTK-m are: Piston which focused on efficient and portable algorithms, Dax which provided a top-down framework that simplified development, and EAVL which provided advanced data structures. The ingenuity and persistence of the VTK-m developers led to the single framework described above and thus eliminated much duplication of effort. This enables very large scale analysis and visualization, such as taking advantage of GPUs to find cosmology halo centers performed on a half-trillion particle simulation run on 16,384 nodes. This led to the ability for the first time to measure concentration-mass relation from a single simulation volume over such an extended mass range.

The details of complementary work to have VisIt and ParaView interoperate with VTK-m is described in section 3.3.1. These sections also describe other scaling activities. Examples of VisIt accomplishments include: accelerating AMR visualization for FastMath applications, developing special crack-free isosurface extraction for ice sheet simulations, and extracting and visualizing features from one trillion particles for a magnetic reconnection application. Similarly, examples of ParaView accomplishments include: providing *in situ* analysis with CosmoTools, visualizations of helium bubbles and tungsten cavities, and extracting, tracking, and visualizing vortex dynamics for a superconductor simulation.

SDAV also provided a tool that facilitates the development of specialized analysis and visualization on distributed-memory machines. This tool, called DIY (Do-It-Yourself), provides a programming model and runtime for block-parallel analytics for building parallel analysis routines. It decomposes data into blocks, assigns the blocks to processors, and supports communication between blocks. Over the past 5 years, DIY was enhanced to use a special internal structure that balances the computation on the processors, thus achieving great efficiency, as high as 50 times faster than the previous version. Because of the high efficiency of the tool, it was used to develop specialized libraries that require a high degree of computation, including libraries to compute parallel Voronoi and Delaunay tessellations of particle datasets, N-body simulations, molecular dynamics codes, and LIDAR point clouds. DIY is shaping up to be the solution for inter-node parallelism within VTK, while VTK-m addresses intra-node parallelism.

SDAV activities include flow visualization methods, described in section 3.3.3. These tools allow researchers to analyze and visualize particles paths and are needed in applications such as in ocean, climate (ice flow), combustion, and fusion. This section describes new methods to compute the shrink and stretch lines which are found by evaluating the associated eigenvectors, methods to increase accuracy for uncertainty in particle tracing, *in situ* identification of salient flow features, and techniques for accelerating flow visualization on GPUs.

Volume rendering is a powerful tool for visualizing complex 3D flow fields. SDAV provides such tools to the scientific community (see section 3.3.4) and enhanced these tools based on user needs and advanced architectures. This section describes tools that were developed and enhanced to support specific needs of the scientific communities we interacted with. For example, techniques were developed in VisIt in cooperation with NVIDIA to avoid copying data between the CPU and the GPU, which led to a highly efficient new compositing algorithm. Other work was to develop rendering algorithms for AMR that are applicable to climate modeling, fusion simulations, and astrophysics simulations, among others. Another special rendering method was developed for an advanced illumination method for interactive visualization of 3D unstructured-grid data. This 3D visualization enhancement is timely as unstructured grids are becoming increasingly popular for a variety of scientific simulation applications. In addition, SDAV has been developing and employing a tool that is optimized for parallel particle rendering, called v13. During the SciDAC-3 period, it evolved to render very large AMR datasets, to support large-scale ray casting volume rendering, and was coupled to molecular simulation code (LAMMPS) to provide *in situ* visualization of large-scale atomistic data.

More recently, we have tackled a difficult area that aims to represent visually the uncertainty of ensemble simulations. Specifically, given a set of related simulations where initial parameters may vary or different

models are run (referred to as ensembles), the problem is how to best represent the uncertainty. To support this capability, a new operator was developed in VisIt, called “Statistical Trends”. It allows for a user to apply different statistical functions to look for trends in data over time. In addition, a new method was developed for determining the uncertainty in the models by comparing each ensemble to a Bayesian Model Average. This method helps to determine where the simulation outputs produce viable distributions. This work was used to determine uncertainty in climate simulations as well as groundwater simulations of uranium seepage.

Finally, the SDAV institute’s productivity deserves special mention, not only in terms of tools developed and applied to a large number of application domains, but also culminating in 451 papers published over the 5 year period, and over 60 tutorials given in major conferences and other venues (see section 4.3). Most of the tools are installed and used routinely on DOE’s leadership-class computing facilities: ALCF, OLCF, and NERSC (see section 4.2 for details). The 38 highlights shown on the SDAV web site (see: <http://www.sdav-scidac.org/highlights.html>) provide an insight into the breadth of technologies as applied to a large variety of scientific applications.

3 SDAV Achievements

SDAV has multiple technologies that fall into the following categories: I/O Frameworks, *In Situ* Processing, Indexing/Compression, Statistics and Data Mining, Analysis and Visualization Frameworks, Analysis and Visualization Libraries, and Multi-/Many-core Visualization Libraries. The technologies that fall into each category are available through our web site (<http://sdav-scidac.org/toolkit.html>) along with documentation, user guides, and points-of-contact information. These technologies (frameworks, tools, libraries) are referred to throughout this report without introductory materials because these were provided in previous reports, and are readily available at the SDAV web site).

All the publications mentioned in this report are can be found on the SDAV web site (<http://sdav-scidac.org/publications.html>), and in the Appendix.

3.1 Data Management

The data management activities within the SDAV Institute have generated new technologies and frameworks for I/O management, in situ processing, code-coupling, indexing, compression, parallel I/O, and file formats. These have significantly improved DOE application scientists’ ability to efficiently manage their data, in a variety of science applications, including fusion science, climate, cosmology, and combustion.

3.1.1 I/O Frameworks

3.1.1.1 ADIOS (ORNL)

Our research was focused on the following areas: integration of *in situ* analytics and visualization into Input/Output (I/O) frameworks, high-level query interface for large datasets, and enhancement of writing and reading data in large scale simulations. In all three areas we have had great results that were published at various conferences. We have worked extensively with the Rutgers and Georgia Tech teams to research and develop *in situ* processing capabilities, and integrated our tools (DataSpaces, FlexPath and ADIOS) to provide a framework for users. We have worked together with the LBNL and NCSU teams to design a query interface for finding and reading the data of interest in large datasets. We integrated our tools (FastBit, ALACRITY and ADIOS) and developed the indexing and querying capability for the I/O framework. We have improved traditional file-based I/O as well by using information about the network topology of the LCF machines (Mira and Titan) and by aggregating write and read operations spatially and temporally that decrease the load on file servers.

During the five years of this project, the ORNL team has regularly released the ADIOS software that

made our research results available to the users. Our products included a unified API for staging and file I/O, a staging solution, a visualization schema, and an I/O-skeleton application generator with standardized measurement; a new aggregated read method that scaled up better than the original method, a staged writing tool used by applications for asynchronous I/O, and spatial aggregation for output; a transformation layer providing various lossless compression and local data reorganization techniques, integrated visualization routines using EAVL/VTK-m, and extensions to support Adaptive Mesh Refinement; improved topology-aware I/O on Bluegene/Q and Titan, wide-area-network staging; Python/Numpy interface and tools; the Query and Indexing interface, supporting three implementations based on FastBit, ALACRITY and on simple min/max statistics, a recovery tool for damaged datasets, and staging I/O at the full scale of Titan; lossy compression with ZFP (Peter Lindstrom at LLNL), and temporal aggregation for improved output I/O overhead.

The team has also been interacting with many applications and scientists using DOE resources over the project period and helped them integrating ADIOS into their applications for their data processing needs: XGC (SciDAC EPSI project, C.S. Chang, PPPL), PIconGPU (Michael Bussman, HZRD), SPECfem3D_GLOBE (Jeroen Tromp, Princeton Univ.), RTM (Pierre-Yves Aquilanti, Total E&P Research & Technology USA, LLC), LAMMPS (Steve Plimpton, Sandia), OpenFOAM (Yi Wang, FM Global), QMCPack (Paul Kent, ORNL), BoxLib/LMC (Marc Day, LBNL), Warp (Remi Lehe, LBNL), Qlg2q (Min Soe, RSU), Chombo (Brian Van Straalen, LBNL), S3D (Jackie Chen, Sandia), Chimera (Bronson Messer, ORNL), AWP-ODC (Yifeng Cui, UCSD), M3D-K (Gou Yong Fu, PPPL), Fine/Turbo (Mathieu Gontier, Numeca), GTS (Stephane Ethier, PPPL), GTC-P (William Tang, PPPL), Pixie3D (Luis Chacon, LANL).

Moreover ADIOS with DataSpaces and FlexPath was used in *in situ* coupled applications and staging I/O. These included nuclear waste disposal (EFRC-WastePD project, Wolfgang Windl, OSU), combustion (Jackie Chen, Sandia), fusion (SciDAC-EPSI, C.S. Chang, PPPL), subsurface modeling (Mary Wheeler, Univ. Texas), replica exchange (Emilio Gallicchio, CUNY) and fluid flow using FEM + AMR (Baskar Ganapathysubramanian, Iowa State Univ.).

For the great number of applications using ADIOS with great improvements to their I/O needs, the ORNL team received an R&D 100 Award in 2013. The ADIOS software is available at the OLCF software website, along with GitHub. We have over ten collaborating institutions contributing to the ADIOS code-base, and are constantly adding new features while retaining rigorous testing and Quality Assurance. ADIOS releases can be found at the ORNL website: <https://www.olcf.ornl.gov/center-projects/adios/>.

3.1.1.2 GLEAN (ANL)

GLEAN facilitates simulation-time data analysis and I/O acceleration. It takes application, analysis, and system characteristics into account to accelerate I/O and to interface with running simulations for *in situ* analysis and co-analysis with zero or minimal modifications to the existing application code base. For I/O, GLEAN fully exploits the topology of the system interconnects and algorithms to reduce the global synchronization for improved performance.

GLEAN components and algorithms are routinely used by the HACC Cosmology science application for production science runs on the various DOE Supercomputing computing systems, including at ALCF and OLCF. The GLEAN I/O is used as part of the HACC I/O CORAL benchmark. This benchmark is used in the DOE CORAL project performance evaluations. We have worked closely with IBM to incorporate GLEAN's topology-aware data movement, reduced synchronization algorithms, and I/O aggregator placement heuristics in the IBM Blue Gene/Q ROMIO implementation of MPI-IO. This has been integrated by IBM and has resulted in multi-fold improvement over the existing implementation. Furthermore, topology aware I/O mechanisms of GLEAN has resulted in multi-fold improvements for the WRF I/O benchmark (Weather Research and Forecasting Model – often used by weather/climate scientists) on the ALCF Blue Gene/Q system as well as on the NERSC Edison system.

Our work in I/O acceleration has resulted in several publications and is part of a Gordon Bell Finalist in 2013. For *in situ* analysis, we have formulated coupling of *in situ* analysis together with an application as a mathematical optimization problem taking into account the system resource characteristics and the characteristics of the application and the various analytics. This has been tested on the Blue Gene/Q system with the LAMMPS and FLASH simulation, and has resulted in an optimal *in situ* workflow for the applications. This has also resulted in publications at Supercomputing 2015 and 2016. Additionally, GLEAN technology was a critical component of the best paper award given at 21st ACM Symposium on High-Performance Parallel and Distributed Computing (HPDC) 2013.

In conclusion, topology-aware I/O is critical in order to achieve scalable performance on leadership supercomputing systems. For *in situ* analytics, we demonstrated that one needs to carefully co-schedule these with simulations taking into account resource characteristics, application characteristics, and the objectives of the analytics. These two areas need more research so as to account for future system characteristics as well as to meet the goals of new applications and analysis.

3.1.1.3 Darshan (ANL)

Darshan is a lightweight I/O characterization tool that transparently captures I/O access pattern information from scientific applications. Darshan can be used to tune applications for increased scientific productivity or to gain insight into trends in large-scale computing systems.

As part of the SDAV project, Darshan has evolved to provide seamless support for a variety of computing platforms, including IBM BG/P, IBM BG/Q, Cray XE, Cray XC, and Linux clusters. The Darshan development team has produced frequent production-quality software releases, culminating most recently in the latest release in November 2016. Darshan is now poised for future deployment on pre-exascale and exascale systems, notably by adopting a modular architecture that enables rapid integration of instrumentation for upcoming data libraries and system services. A regression test suite has also been created and is executed nightly on production infrastructure at ANL for ongoing validation as new capabilities are added.

Darshan is used at the majority of the world's large-scale computing facilities, including officially supported installations at the ALCF, OLCF, and NERSC. The ALCF and NERSC have notably enabled Darshan for automatic instrumentation of all production jobs by default. This broad adoption has enabled Darshan to play a critical role in improving the performance of numerous critical applications and libraries, including HACC (cosmology), Flash (astrophysics), CESM (climate), and HDF5 (data management).

3.1.2 *In Situ* Processing and Code Coupling

3.1.2.1 DataSpaces (Rutgers)

The SDAV team at Rutgers University focused on designing, developing, and deploying in-memory data staging on leading DOE systems and integrating them with applications. Specifically, the Rutgers team focused on designing and implementing programming abstraction models as well as underlying adaptive runtime management strategies and developed the DataSpaces tool to support scalable hybrid staging. Hybrid staging uses resources (CPU and memory) on nodes running the applications as well as on dedicated nodes to stage, reorganize, and manipulate data. It enables multiple codes running on the same system that are part of a workflow to exchange and transform data in-memory. The Rutgers team also explored the in-memory staging-as-a-service deployment model. The overarching goal of the effort was to enable applications to construct more complex end-to-end coupled simulation workflows. Key research and development achievements include:

- Design, development, deployment, dissemination and evaluation of the DataSpaces scalable hybrid staging framework on leading DOE systems and its integration with ADIOS

- Design, development and evaluation of autonomic runtime mechanisms in DataSpaces for the optimization of staging-based *in situ* (and *in transit*) workflows, including mechanisms for staging-based (DART) and point-to-point (DIMES) high-throughput/low-latency asynchronous data exchange, task placement and scheduling in hybrid staging, data placement and movement across deep memory hierarchies, dynamic code deployment, staging over LANs and WANs, and a service-based abstraction for staging
- Integration of DataSpaces with applications to support end-to-end loosely and tightly coupled application workflows (including integration of online analytics) in a range of application domains including Fusion, Combustion, Subsurface Modeling, Fluid Dynamics, Chemistry, and Material Science.

The DataSpaces-related activities have led to the dissemination of the DataSpaces software, its deployment on supercomputing systems at ORNL, ANL and NERSC, and its integration with ADIOS, as well as 22 publications, 10 keynotes/plenary presentations, and 16 invited presentations. The Rutgers PI served as chair or in another leadership role for 14 conferences/workshops. The project enabled the research of 5 Ph.D. students (2 graduated) and 1 Postdoc.

The project demonstrated that staging can effectively address data-related challenges at very large scales and can efficiently enable coupled simulations and novel *in situ* application workflows across a range of applications areas.

3.1.2.2 FlexPath (GTech)

Over the 5-year period Georgia Tech (GT) has made a number of contributions to the state of the art in *In Situ* Processing and Code Coupling. The core of these efforts have been in creating the FlexPath (originally FlexIO) data staging transport for ADIOS. Flexpath is a type-based publish/subscribe infrastructure for coupling high-end scientific applications with their online analytics services. Flexpath's pub/sub approach makes possible runtime configurability, scalability, and also fault tolerance, as the pub/sub abstraction allows for the decoupling of diverse analytics components, permits multiple subscribers or publishers to share a single data stream, and suppresses communications for cases in which there are no subscribers to certain data streams (e.g., those not of current interest). These properties contrast with the typical assumptions made by communication infrastructures like MPI, where the domain of executing processes is initialized at launch and cannot grow or shrink for the remainder of the execution. This technical contribution is achieved by using direct connections between interacting components, including the scatter-gather or MxN communications needed across different communicating internally parallelized analytics components.

Architecturally, FlexPath is built using EVPath, an event transport middleware layer that is released as open source software for the developer community. Specifically, it is designed to allow for the easy implementation of overlay networks, with active data processing, routing and management at all points in the overlay. During the duration of the SDAV project, Georgia Tech created and/or tuned three pluggable EVPath transports to make use of new networking technologies. These transports include a raw InfiniBand transport that directly used the Verbs interface. Another transport was based upon NNTI, the RDMA transport developed at Sandia National Laboratories to support the TRIOS system and capable of running across both Infiniband and the uGNI interconnect for Cray machines. Lastly, to leverage industry commitment to a unified communication interface, GT developed an EVPath transport based upon the emerging 'libfabric' interface that supports many current and emerging RDMA networks.

Flexpath is deployed for use across a range of high end machines, including ORNL's Titan machine, Infiniband clusters, and commodity scientific computing engines. It has been a part of official ADIOS releases since 2013. Flexpath has been used for code coupling or *in situ* processing with a variety of scientific applications, including LAMMPS, GTS, S3D, Maya and PIconGPU. We also created Flexpath-enabled visualization plugins for VisIt. In 2014, the Georgia Tech SDAV team was involved in

a demo at SuperComputing 2014 in New Orleans that involved the A*STAR Computational Resource Centre in Singapore and a trans-oceanic InfiniBand link, demonstrating SDAV technology capability on a global scale. In the GT-led demo using FlexPath, the Sandia-led molecular dynamics code LAMMPS ran in Singapore, sent data to an analysis workflow hosted at GT, the output of which was then delivered to a VisIt-based display in New Orleans. In addition, GT supported the hosting of SC demonstrations in 2014, 2015, and 2016 for experimental fusion data processing, developed at ORNL and LBNL, and automated tumor labeling in images, developed at Stony Brook. All three of these ADIOS-based demonstrations utilized transports that depended on one of GT's SDAV software stacks, EVPath.

Additionally, motivated by end scientists' requests for development of a scalable/portable way to access their data on end devices, Georgia Tech created a new staging method for ADIOS, utilizing the in-line indexing and analysis methods that already existed, but based with storage in cloud environments like Amazon's EC2. This "SciBox" project offers the ability to bridge to an interesting array of scientific analysis and visualization usage scenarios that are not yet well understood from a platform perspective.

3.1.3 Indexing

3.1.3.1 FastQuery and Indexing (LBNL)

Over the past five years, FastQuery indexing and querying software has been extended in a number of ways to meet the applications' demand [Lin2013a]. It has been shown to scale well in extracting information from massive amounts of data stored in scientific file formats such as HDF5 and ADIOS-BP. Our work has produced more than 20 technical publications. In this brief summary we highlight its uses in three DOE science applications: plasma physics simulation, ice sheet modeling, and particle accelerator design modeling.

Magnetic reconnection is an important mechanism that releases enormous energy as field lines break and reconnect in plasmas. To understand this phenomenon, plasma physicists run large-scale simulations and track the trajectories of trillions of plasma particles through a magnetic field. However, they are particularly interested in a relatively small numbers of highly energetic particles (still in the millions) at the intersections of magnetic field lines. Locating these particles from the trillions of particles was a challenge for the physicists. FastQuery software was able to index more than a trillion particles in about 10 minutes and then locate those particles in a few seconds [Byn2012a]. This capability to locate the "interesting" particles in seconds gave the physicists a new way to analyze magnetic reconnection.

In ice sheet modeling, an important task is to identify the icebergs that are breaking away from the ice sheet. This is known as the ice calving problem. The existing approach goes through each cell of the ice sheet model repeatedly, which can be very time consuming. We divided the ice calving problem into two steps, first to identify cells with thick ice, and then to connect these cells into connected regions. The regions of ice that are not connected to the ice sheet are labeled as icebergs. FastQuery could easily handle the first step, but we had to develop the algorithm for the second of identifying connected regions in adaptive mesh refinement (AMR) data. We developed an efficient parallel connected component labeling algorithm. Overall, we were able to accelerate the ice calving calculation by a factor of 6 [Dev2016a, Zha206a, Zou2016a].

In working with accelerator design software, FastQuery was used to track particles that stray away from the center of the particle accelerator. These particles are known as halo particles among the accelerator designers. In this case, FastQuery indexed billions of particles over about 800 time steps to support the user queries. The query results revealed an unexpected increase in the number of halo particles, which gave the designers a chance to correct the problem and reduce the number of halo particles [Chi2014a].

In conclusion, responding to scientists' needs, led us to enhance the FastQuery software and turn it into a powerful parallel search engine that was used on many problems in various scientific domains. We expect in the future to apply this tool to additional scientific domains, which inevitably will have unforeseen challenges.

3.1.4 *In situ* data compression

3.1.4.1 Analytics-driven data layout optimizations and Compression (NCSU)

Over the 5-year period, we have been working on a number of issues that address scientific data indexing, compression and storage layout problems. Moreover, in addition to focusing on mainstream uniform mesh data, we have also addressed Adaptive Mesh Refinement (AMR) data.

In the domain of indexing and query, we first developed ALACRITY [Jen2012a]. It produces an inverted index and index metadata, by exploiting floating point number representation. It performs at speeds suitable for in-situ processing (150-225MB/s), while maintaining a small data footprint (data+index < 125% original data). Based on ALACRITY, we have developed DIRAQ [Lak2013a], a parallel, scalable, *in situ* indexing technique. It enables smarter group-level index aggregation, which not only improves later query performance by generating less-fragmented indexes, but also achieves increased end-to-end write throughput due to overall data compression.

For compression, we developed a hybrid compute-I/O interleaving for in-situ parallel lossless compression technique, ISOBAR technology [Sch2012]. It can reduce the total time-to-disk by 12-46%, according to tests over real scientific data. Moreover, we have extended our earlier work on ALACRITY encoding [Jen2013a], by integrating inverted index compression and data reduction, resulting in a full-precision, query-optimized data representation that is 55-90% of the original data (for FLASH, S3D, XGC, GTS datasets). This includes a light-weight index that is 5-20% of the original data.

Regarding storage layout, we've developed MLOC [Gon2012a, Gon2012b], which provides flexible, interchangeable data layout optimizations for heterogeneous access patterns, allowing users to match data access patterns to their particular needs. Based on MLOC, we've developed a run-time multi-level data layout optimization framework (PARLO) [Gon2013a], which is integrated with ADIOS to achieve high-performance *in situ* data layout optimization at runtime. Moreover, we have extended ADIOS to include a generic, user-transparent data transformation framework that allows end users to apply *in situ* data transformations without changing their existing application [Boy2014a].

Moreover, we have studied various indexing, storage layout and I/O issues for AMR data. We have developed an indexing and querying framework to facilitate large-scale AMR data scientific discovery and exploration [Zou2016a]. It has an AMR-specific hybrid index methodology which captures both spatial and value aspects of the AMR data, and enables efficiently processing queries that have both a spatial selection and value constraints. We have also developed an *in situ* storage layout optimization method for AMR spatio-temporal read accesses [Tan2016a]. This work enables automatic selection from a set of candidate layouts based on a performance model, and reorganize the data before writing to storage. Moreover, in order to facilitate runtime AMR data sharing across scientific applications, we have developed AMRZone [Zha2016a]. It enables efficient in-transit AMR data analytics, by constructing a virtual and distributed staging space to avoid accessing data over a file system.

Given the rapidly growing volume of scientific data, data access latency reduction can greatly improve the performance of applications. According to our experience, data indexing, compression and storage layout can help to significantly reduce data access latency, by decreasing data size and facilitating specific queries.

3.1.5 Parallel I/O and file formats

3.1.5.1 PIDX (UUtah)

Over the lifetime of the project, we have developed a new capability implemented in the PIDX library. It involves a data movement and I/O infrastructure that has unique scaling properties on DOE

supercomputers while allowing fast querying for data analytics remote streaming. The PIDX library has been installed and used on other supercomputers to demonstrate its effectiveness on a broader range of hardware platforms. In general, the PIDX library enables HPC applications to write distributed multi-dimensional data directly into a hierarchical multi-resolution data format with minimal overhead. Production read/write of restart dumps and remote streaming has been demonstrated at the exhibit floor of the Supercomputing conference for the last three years. For example, three installations at the DOE booth, the Utah booth, and the KAUST booth have shown direct use and remote monitoring of distributed processing including the Mira supercomputer at Argonne, Shaheen II at KAUST and the CHPC in Salt Lake City. In addition, a server at Lawrence Livermore National Laboratory was used to give real time access to petascale climate modeling data housed on NASA storage. These demonstrations have shown the complete workflow of a simulation running and rendering data live at a remote site (in this case SC exhibit floor) during its execution.

The most recent work include scaling runs on the entire MIRA machine (up 768k cores) while achieving a sustained data transfer equal to 80% of the nominal I/O bandwidth of the hardware. The PIDX library is now available to the general public (webpage <http://www.cednav.com/research/project/15-pidx.html>) with an open source release accessible via the following GIT repository <https://github.com/sci-visus/PIDX>.

To complement the deployment of the I/O library for simulation, the team has deployed plug-in components that make it easy to use the file format in practice. This includes the VisIt distribution which now integrates a ViSUS reader that allows one to directly read files generated by the PIDX library. Moreover, the VisIt tool can directly take advantage of the multiresolution nature of the data format and by default loads a coarse version of an input to allow access to data that is potentially too large to fit in memory.

Future developments of the PIDX project will involve effective use of reduced precision and compression techniques to minimize the data movements. In addition, recent tests show that the PIDX library can also take advantage of novel hardware like the burst buffer, although more work is needed to reach a production quality deployment. We are also working towards extending the PIDX framework to support particle data.

3.1.5.2 ROMIO (ANL)

The ROMIO MPI-IO implementation, provided on virtually every HPC platform and used internally by HDF5 and PnetCDF, continues to provide the foundation of the HPC I/O software stack.

The fundamentals of ROMIO have been well-tested over 15 years. In SciDAC-3 we focused on improving ROMIO's behavior at scale.

- Very large data descriptions were overflowing internal MPICH and ROMIO data structures and overwhelming some operating system routines. We audited the code for overflow conditions and devised workarounds for the operating system issues.
- ROMIO internal data structures could in some cases consume large amounts of memory. We experimented with compressing those data structures. The work demonstrated dramatic reduction (1.1% of original size) in peak memory overhead with a trade-off of 25% higher CPU time to process these data structures.
- We worked in collaboration with IBM to better tune ROMIO at the large scales of our Mira Blue Gene /Q machine. We also worked with applications to make better use of the MPI-IO interfaces ROMIO provided. These tuning and algorithmic tweaks improved performance in some cases by as much as a factor of 15.

The ROMIO team have conducted numerous tutorial at major conferences (such as Super Computing), and wrote multiple papers on major improvements to the system, its use by other tools, such as MPI and Parallel-NetCDF, and its effect on various scientific application codes [see recent publications: Lat2017a,

Luo2015a, Sny2015a, Ham 2014a].

Storage systems continue to increase in complexity, with larger numbers of devices and new software and hardware components. ROMIO continues to provide an abstraction layer to hide these complexities. As new concepts such as burst buffers and I/O forwarding shift from research topics to deployed components on supercomputers, ROMIO must continue to evolve to meet this new landscape. Ongoing open research issues are how to build upon ROMIO's strengths while minimizing overhead at growing core-counts, how to carry out background I/O while not disturbing computational science applications, and identifying additional programming models which would benefit from ROMIO's proven algorithms.

3.1.5.3 Parallel netCDF (NWU)

Parallel netCDF (PnetCDF) is an I/O library that supports parallel data access to netCDF files. NetCDF, developed at Unidata, defines a self-describing and portable file format and a set of application programming interfaces (APIs) for storing and accessing scientific data. However, its APIs do not support parallel I/O to files in the classic netCDF file format. Starting from version 4.0, NetCDF chose HDF5 as the underneath mechanism to add parallel I/O feature, but the file format must be in the HDF5 format. To support parallel I/O for the classic format which is being used by the majority of user communities that use NetCDF in climate, geoscience, and others, PnetCDF was developed to enable parallel I/O to the netCDF files in classical formats with high performance on large-scale parallel computers.

For the past five years, the PnetCDF software has been continuously released to the public as open source, through five major releases, the last of which was in December 2016. Many important features based on user requests and performance enhancement have been developed and incorporated into the software, including support for C++ and Fortran 90, a new set of non-blocking APIs, a request-aggregation technique to enhance performance, and a new extended classic file format, named CDF-5. The CDF-5 format supports definitions and access of large variables with more than 2 billion elements.

Collaboration between PnetCDF developers and the netCDF team at Unidata has continued since 2015 with the focus of developing a software component in the netCDF library to enable it to read/write CDF-5 file format, in both sequential and parallel. Because netCDF has a much larger user group across different disciplines, such collaboration significantly leverages the broader impact of PnetCDF. The CDF-5 feature has been made available in a release of netCDF in January 2016.

We also established collaboration with the PIO (Parallel I/O) library developer team at the UCAR. The PIO library is used by the CESM and ACME projects, two major earth and climate system modeling frameworks funded by DOE. This collaboration involves developing new APIs in the PIO library based on user requests and performance/bug tracing in the underneath MPI-IO library.

We have initiated a collaboration with the System Software Research Team, led by Dr. Yutaka Ishikawa, at the RIKEN Advanced Institute for Computational Science in Japan. The purpose of this work is to investigate the I/O software and storage system performance on the K computer. We have developed a PnetCDF I/O module for a production real-time climate simulation application named SCALE developed by the climate scientists at RIKEN.

In the past five years, the PnetCDF library building process was improved and now supports various vendor compilers. The library is available on all DOE production parallel machines at ANL, ORNL, NERSC, etc. We plan to continue the PnetCDF development and maintain the established collaboration by reaching out to more application domain scientists and explore the opportunities for improving and expanding the PnetCDF library to support high-performance computing, data analysis, and parallel I/O.

3.2 Data Analysis

The data analysis activities of the SDAV Institute have yielded a number of novel algorithms and software tools that support numerous DOE SciDAC application scientists in fields including astrophysics, climate, combustion, climate, cosmology, fusion, and development of nano-materials. These include tools for visual exploration, topological data representation, flow field analysis, and feature-driven exploration.

3.2.1 Visual Analysis and Exploration Techniques

3.2.1.1 Large-Scale Volumetric Feature Exploration (UCD)

Distance fields play a critical role in visualizing and analyzing complex data and have applications in feature extraction, computer graphics, data indexing, and compression, and they can be used as “importance” fields to direct analysis and reduce data, especially in large volume datasets. We have developed a highly efficient parallel distance field construction algorithm to make it usable for large-scale *in situ* applications. Experimental studies on Hopper, a Cray XE6 supercomputer, using a large geometric model consisting of 350 million triangles demonstrate an overall parallel efficiency at 75.26% from 1024 to 8192 CPU cores. Studies on Hopper using a temperature isosurface from a turbulent combustion simulation demonstrate perfect parallel efficiency from 4320 to 34560 CPU cores. We have achieved the most scalable parallel distance field calculations. Such high efficiency is achieved with a new distributed spatial data structure, which we call *parallel distance tree* to manage the level sets of data and facilitate surface tracking over time, resulting in significantly reduced computation and communication costs for calculating the distance to the surface of interest from any spatial locations. The resulting technology can benefit many SciDAC application areas such as astrophysics, climate, combustion, cosmology, and fusion. A paper reporting this work was published in IEEE Transactions on Visualization and Computer Graphics [Yu2015a].

In addition to the distance field work, we have also developed volume feature extraction techniques for large-scale data that can function on a standard desktop PC. Such techniques allow researchers to reduce data based on their domain knowledge. Since it's still commonly desired by scientists to use their desktop PCs for data visualization and analysis tasks, an *in situ* data preparation solution to support interactive feature extraction from large-scale volume data is needed. We have developed an *in situ* supervoxel generation method, together with a new hybrid feature extraction technique which combines GPU-accelerated clustering with the multi-resolution advantages of supervoxels in order to handle large-scale datasets on standard desktop PCs, which usually have limited memory and bandwidth capacity. The method is based on a user-driven uncertainty-based refinement approach to keep extraction results at the desired level of detail. We demonstrate the effectiveness and interactivity of this technique with a number of application specific examples. A paper reporting this work has been presented at LDAV 2015 (receiving a best paper honorable mention) [Xie2015a].

Technologies like these have a broad impact on a variety of SciDAC research areas and can help to achieve the goal of enabling sophisticated volume feature exploration in large-scale data. Our work opens future research directions that involve developing polished visualization software packages that incorporate these techniques.

3.2.1.2 Visual Analysis of Large-Scale Trajectory Data (UCD)

We have developed new analytical means of exploring particle and trajectory data commonly found in SciDAC applications. First, we developed Ultravis-P for interactive visual analysis of trajectory data derived from 3D vector fields or large-scale particle simulations. It is composed of a powerful back-end engine for parallel clustering/classifying curves and a light-weight, front-end user interface for interactive analysis. Our parallel regression-model based clustering/classification algorithm can use a combination of

GPUs and CPUs. On GPU clusters such as *Dirac* at NERSC and *Lens* at ORNL, the parallel algorithm demonstrates scalable performance with millions of trajectories. We have used this system to analyze particles' behavior in turbulent combustion simulations [Wei2012b]. We have also added functionality for analyzing trajectory data derived from fusion simulations according to their geometric properties [Sau2013a].

Furthermore, we have also explored how interactions between particle/trajectory-based data and field-based data can enhance this type of analytical exploration. We have introduced a new trajectory-based flow feature tracking method for joint particle/volume datasets. This method utilizes the indexed trajectories of corresponding Lagrangian particle data to efficiently track features over large jumps in time. As a result, this method is especially useful for situations where the volume data is either temporally sparse or too large to efficiently track a feature through all intermediate timesteps. We tested our method using combustion and atmospheric datasets. A paper reporting this work has been presented at IEEE SciVis 2014 conference [Sau2014a] and was also invited to be presented at ACM SIGGRAPH 2015.

To further enhance this type of analysis, we have also developed a joint Eulerian-Lagrangian framework aimed at supporting operations that utilize both particle and volume data simultaneously. More specifically, the data organization schemes developed allow one to quickly query, sample, and operate with both reference frames in a large-scale setting and, if necessary, in an out-of-core manner. We have demonstrated the effectiveness of this new framework using a number of large-scale datasets provided by SciDAC science projects in cosmology, combustion, and fusion. A paper reporting this work was published in IEEE Transactions on Visualization and Computer Graphics [Sau2016a].

Recently, we have expanded this joint analysis to explore spatio-temporal features in both a particle and volume reference frame. Users begin with a feature of interest in one reference frame as a spatio-temporal origin and can extend analysis temporally into the opposing reference frame. This allows users to extract and explore features describing the interplay between both particle and volume data in space and time. This work also explores new ways of visually presenting such a feature to a user. A paper describing this work has recently been accepted by the PacificVis 2017 conference and will appear in IEEE Transactions on Visualization and Computer Graphics.

Alternatively, in a joint effort with scientists and Princeton Plasma Physics Laboratory (PPPL), we have been exploring the use of histograms to capture the velocity decomposition of particle data. This has important applications to Lagrangian-based flow data analysis since traditional visualization techniques are often subject to a trade-off between visual clutter and loss of detail, especially in a large scale setting. We showed that the use of 2D velocity histograms can alleviate these issues. We demonstrate our design with an interactive system to visualize the velocity decomposition of particle data from fusion simulations. We consider both a post-hoc setting with an on-the-fly sampling scheme and an *in situ* setting to maintain interactivity in extreme scale applications. A paper presenting our design and case studies published in the 2015 LDAH Symposium (receiving a best paper honorable mention) [Neu2015a].

We have also extended this work in developing new ways to explore time-varying properties of the 2D histograms. This is done by stacking the histograms over time into a 3D volume and using isosurfacing techniques to explore time-varying properties of the captured distributions. In this case, the isosurface represents a boundary between histogram bins with higher/lower frequency of samples compared to the isovalue. Furthermore, improvements have been made to the system's ability to select groups of trajectories based on features in the histogram distributions. A paper reporting this work was published by IEEE Transactions on Visualization and Computer Graphics [Neu2016a]. We are currently working on deploying a polished visualization software to scientists at PPPL and plan to conduct a thorough usability study. Such a study will help us improve the system and answer fundamental questions about user perception and understanding of this new technology.

3.2.2 Topological Methods

3.2.2.1 Topologika: Topological Techniques for Scientific Feature Extraction (UUtah)

Over the last five years we have been developing a number of topologically based analysis techniques to extract and track features in a broad class of scientific applications. Some of these techniques are part of different software infrastructures (MSCEER, ND²AV, TALASS) discussed in more details below. Other techniques are aimed at developing new application use cases and research prototypes targeted at individual scientific applications. Over the duration of the SDAV institute we have seen these techniques mature from the first *in situ* and in-transit analysis approaches [Ben2012b] to massively parallel implementations [Lan2014a] able to process an order of magnitude more information than previous approaches at less than 1% of the overall simulation costs. Simultaneously, these techniques have become accepted in the scientific main stream, leading to numerous publications in application focused journals [Gro2012a, Gro2013a] as well as open source code releases [Bre2016b] and integration into community tools, i.e. VisIt.

Topological analysis is the focus of an application partnership with a team from the BES office concerned with the analysis of first principle molecular dynamics simulations. This has already led to a joint publication [Bha2016a] with multiple others currently in submission. Finally, we have explored extending structural analysis to vector fields [Bha2014a, Bha2014b].

Going forward there are three clear directions to pursue: a) the continued shift towards *in situ* analysis will require concerted research and software development efforts to create the corresponding algorithms and implementations. These efforts will also provide a great opportunity to collaborate more closely with ongoing efforts in the exascale research project as well as run time focused projects; b) as topological techniques are becoming more accepted there will be continuous need to modify and adapt both the approach as well as the implementations to new research areas and simulation codes. Prime examples are the new MPAS grids of the high resolution climate models but opportunities also exists in molecular dynamics, biology, healthcare, etc.; c) a number of research areas in applications such as particle physics and turbulent flow can benefit significantly from topological techniques but will require the development of new approaches.

3.2.2.2 MSCEER: Morse-Smale Complex Extraction Exploration and Reasoning (UUtah)

One of the specific tools resulting from the five years of work is MSCEER, a set of software libraries and tools for data analysis and visualization based on the specific topological construct of the Morse-Smale Complex. This tool has been effective in the analysis of a number of scientific domains ranging from clean combustion [Gyu2014a] to the design of battery materials [Bha2016a, Gyu2015a, Gyu2015b]. The latter application, for example, has been driven by the representation of Ion Diffusion with DFT (Density Functional Theory) models. The work uses ab initio molecular dynamics (AIMD) simulations, which are increasingly useful in modeling, optimizing, and synthesizing materials in energy sciences. The solved Schrodinger's equation and the generation of the electronic structure of the simulated atoms as a scalar field is ideal for topological analysis based on the computation of the Morse-Smale complex. The discrete nature of the Morse-Smale complex computation used in the MSCEER allows analyzing first-principles battery materials simulations with no loss of precision. We consider a carbon nanosphere structure used in battery materials research and employ Morse-Smale decomposition to determine the possible lithium ion diffusion paths within that structure. Our approach is novel in that it uses the wave function itself as opposed to distance fields, and that we analyze the 1-skeleton of the Morse-Smale complex to reconstruct detailed geometric representations of diffusion paths. Furthermore, it is the first application where specific motifs in the graph structure of the complete 1-skeleton define features, namely carbon rings with specific valence.

For the application to combustion simulations, Morse-Smale crystals (elements of monotone flow in a 3D scalar field) are very well suited to define *dissipation elements*, a structure that has become widely used to

understand turbulent flows [Gyu2014a]. Furthermore, the MSCEER libraries have been adapted and improved to meet specific requirements of various analysis tasks, such as invariance to mesh orientation [Gyu2012b] needed to compute topological elements of combustion simulations, extension to large-scale meshes with distributed computation [Gyu2012a], flexible identification and visualization of individual elements of the Morse-Smale Complex [Gyu2012c], and incorporating numeric integration of gradient trajectories into the robust combinatorial approach [Gyu2014b]. Although developed to solve specific problems for domain-specific analysis tasks, these techniques have proven to be applicable across domains: for instance, the ability to compute geometrically accurate dissipation elements in combustion simulations has been directly applicable to computing accurate Bader volumes in the study of battery materials.

Future developments in this field include scaling to large models without core techniques as well as parallel deployment for *in situ* processing that can lead to scientific insight together with massive data reduction.

3.2.2.3 ND²AV: N-Dimensional Data Analysis and Visualization (UUtah)

Over the 5-year period we have seen a rapidly growing interest in high dimensional analysis and visualization techniques. In particular, many scientific applications are interested in exploring and understanding high dimensional parameter spaces in areas ranging from high energy density physics to nuclear reactor safety. We have developed a suite of generic tools to support these activities that are applicable to virtually all high dimensional data. These include, distortion guided visualization [Liu2014a] and its application to multi-variate volume rendering [Liu2014b], subspace-based visualization [Liu2015a] and a new way to identify important viewpoints in high dimensional data [Liu2016b]. Another line of research has explored the application of these technique to high energy physics [Bre2016b] and Nuclear Safety Analysis [Mal2016a, Mal2015a, Mal2015b] in collaboration with Lawrence Livermore National Laboratory. In addition, we have contributed well-received surveys of high dimensional visualization techniques to the community [Liu2015b].

In the longer term, the significance of high dimensional techniques will increase, driven by needs in uncertainty quantification, risk assessment and sensitivity analysis. This will require more computationally efficient techniques that are easily accessible to the scientific community as well as more intuitive interpretation of the results.

3.2.3 Flow Field Analysis

3.2.3.1 Parallelization of Flow Algorithms for Large-Scale Data Analysis (UCD)

We have been working on the parallelization of flow visualization algorithms, specifically related to integral curve methods. Integral-curve-based algorithms are particularly difficult to implement on distributed parallel systems, as the communication between processors eventually dominates the algorithms, and our results have shown that the computation time is dependent on the complexity of the dataset [Cam2012a]. We also worked on methods for representing flow visualization in particle-based systems. We have demonstrated new analytics for flow in development of the velocity gradient tensor [Obe2012a], and continue to develop new methods based on continuum-mechanics effects [Agr2013a]. This allows us to give the end-user visual information on the “stretching” of time surfaces in the flow.

Furthermore, working in conjunction with our colleagues at Lawrence Berkeley National Laboratory and the University of Oregon, we have developed new methods to store and visualize flow fields by use of flow maps. In general, we showed that a Lagrangian representation for data, where trajectories are kept at each data point, rather than vectors, combined with interpolation of trajectories, allows visualization algorithms to be more accurate, be faster, and use less memory than existing techniques. More importantly, these methods can be used in an *in situ* environment in a much better way than with existing

methods. Our main performance results were presented at the 2014 LDAV Symposium [Agr2014a]. We continued to develop new methods for flow visualization based on this new representation that can be implemented on large-scale parallel systems with additional results presented at the 2015 SPIE Conference [Arg2015a, Arg2015b]. Furthermore, we have adapted these methods to compressible flow models and have papers published in IEEE Transactions on Visualization and Computer Graphics [Cha2015a, Cha2015b]. Next, we flushed out the differences in this representation, and the bottlenecks that are introduced. We have developed methods that utilize curve-based representations as the “data structure” for this method, and have worked out the interpolation methods to define pathlines from this representation. This work was presented at the 2015 LDAV Symposium [Buj2015b].

3.2.3.2 VTK/OSUFlow Integration (OSU)

As part of SDAV’s goal to facilitate large scale flow visualization, our effort was to enhance the OSUFlow library with a scalable stream surface computation algorithm, which was published in SC’14 [Lu2014a]. While several parallel streamline computation algorithms exist, relatively little research has been done to parallelize stream surface generation. This is because load-balanced parallel stream surface computation is nontrivial, due to the strong dependency in computing the positions of the particles forming the stream surface front. In our algorithm, seeding curves are divided into segments, which are then assigned to the processes. Each process is responsible for integrating the segments assigned to it. To ensure a balanced computational workload, work stealing and dynamic refinement of seeding curve segments are employed to improve the overall performance. This is a joint work between OSU and scientists at ANL. We have integrated this algorithm into the OSUFlow library. Another addition to the VTK/OSUFlow library is the ability of interactive manipulation of flowlines and flow article. With a novel deformation model, we allow the user to minimize occlusions and maximize the ability to identify salient flow features [Ton2016a].

3.2.4 Feature-Driven Data Exploration

3.2.4.1 TALASS: Topological Analysis of Large-Scale Simulations (UUtah)

TALASS refers to a software framework to compute, track and explore the spatio-temporal history of features in scientific simulations. Over the 5-year period we have broadened the range of applications to new feature types, i.e. embedded features on surfaces [Wid2015a], new applications, i.e. halo finding [Wid2014a] and new mesh types [Lan2015a]. At the same time we have been hardening the software and deployed it to researchers at Sandia National Laboratory. TALASS, originally designed for turbulent combustion research [Ben2012a, Wid2012a, Wid2015b] has now been extended to astronomical simulations [Wid2014a], weather analysis [Wid2017a], plasma physics [Wid2016a] and health care [Wid2016b]. In addition, the software has recently been ported into the ViSUS analysis framework which allows it to integrate seamlessly topological-based analysis and tracking with large scale visualization.

Going forward, TALASS will require continued investments in the software stack to allow its deployment to a broader community. Furthermore, there exist a number of interesting opportunities to extent the application space into new areas, such as, climate research or health care.

3.2.4.2 Feature-based Analysis of Plasma-based Particle Acceleration Data (LBNL)

Computational accelerator modeling aims to understand the fundamental nature of particle acceleration under varying conditions. When performing such modeling, accelerator scientists generate vast amounts of model output from simulation runs on large-scale HPC resources. The focus of our work has been on enabling scientific knowledge discovery using two different approaches.

The first uses a post-processing approach, and consists of methods for automatic feature detection and

classification to first locate interesting features in time-varying model output, then apply machine learning methods to locate similar features elsewhere in a data collection. In support of plasma-based accelerator modeling efforts, we developed a method and software toolset for automatic detection and classification of particle beams and beam substructures due to temporal differences in the acceleration process [Rub2014a]. The software implementation, *lwfapath*, supports both interactive and batch modes of operations to support different needs and use scenarios of the accelerator modeling community, and has been run at NERSC as well as on desktop-class platforms by accelerator modeling researchers.

The second uses an *in situ* approach, where visualization and analysis methods are coupled directly to an accelerator modeling code to avoid the complications and cost associated with writing, then reading data to/from persistent storage. In support of the WARP code team, we coupled VisIt with WARP to implement *in situ* methods for feature-based data analytics, efficient large-scale data analysis and visualization. This work enabled accelerator modeling researchers to see and analyze, for the first time, high-resolution 3D simulations and compare them with 2D simulations [Rub2016a]. Prior to this work, accelerator scientists were constrained by I/O to study only of 2D simulation models. The new software, *WarpIV*, has been publicly released and is installed at NERSC.

3.3 Visualization

Our well rounded portfolio of visualization activities aims to provide usable visual data exploration and analysis technologies for use by the DOE computational science community. We evolved our two primary visualization applications, VisIt and ParaView, to be multi-/many-core aware, deployed these applications at DOE supercomputing facilities, and provided direct user support to computational science users. We invested in maturing and applying key technologies (PISTON, DAX and EAVL) for achieving multi-/many-core capability over a longer time horizon, and leveraged these into a single software platform, VTK-m, that will have impact on the broader visualization and analysis community for at least the next decade. Finally, we focused on applied development efforts that produce new capabilities, driven by science needs that ultimately end up in software distributed to the computational science community.

3.3.1 VisIt and ParaView

3.3.1.1 VisIt (LBNL, LLNL, ORNL, UO)

Over the five-year period, we made many improvements to the VisIt visualization tool, both in support of new architectures and in new features for SciDAC stakeholders. We also made many releases of our software, and made sure that VisIt was installed and accessible at the LCFs and NERSC.

The most important architectural change for VisIt has been the rapid increase in parallelism within a compute node. At the beginning of SDAV, VisIt only supported MPI-parallelism, which we foresaw as a problem given architectural trends. In response, we have pursued two major activities. First, we have added “pthread”-style threaded parallelism to VisIt. This activity proved to be a promising direction, since many VisIt algorithms could be retrofitted for this type of parallelism with (relative) ease. Of course, this style of parallelism will not work on GPUs, and so this development arc was limited to improved performance on multi-core CPUs and support for the Xeon Phi. A second activity has been the incorporation of VTK-m into VisIt. This activity is the “long term” solution for shared-memory parallelism within VisIt, but also a much larger effort. While this activity is far from complete, VisIt is now able to interact with VTK-m and make use of its algorithms as they become available. As additional functionality is added to VTK-m, VisIt will be in a position to quickly take advantage. Going forward, porting VisIt algorithms to many-core architectures will essentially involve making a VTK-m implementation for that algorithm and then having VisIt invoke that implementation.

In terms of new features for SciDAC stakeholders, there are many activities to report. VisIt now can read SpecFEM3D data (in conjunction with ADIOS), resulting in the ability to visualize their full resolution

data from Titan. VisIt's support for Adaptive Mesh Refinement (AMR) data has greatly improved, especially the type of AMR coming from the FASTMath SciDAC Institute. In particular, VisIt now has production-quality crack-free isosurface extraction, which was used to visualize ice sheets computed using the BISICLES climate simulation code. VisIt also now has an FTLE operator, which was added and optimized for Linda Sugiyama of MIT. We also improved infrastructure that benefits many stakeholders, in particular our *in situ* version of the code (LibSim) and substantial improvements to its particle advection module. To publicize these new features the VisIt team was active in outreach, including participation in 11 tutorials (5 at SC and 4 at ATPESC).

These improvements led to many successful usages of the code by SciDAC stakeholders. Two noteworthy examples are for laser back scatter simulations and magnetic reconstruction simulations. In the first example, VisIt was used to visualize 220 billion cell data and correlate multiple, complex, 3D phenomenon over time to bring out features of interest at key points in the simulation, such as where back scatter phenomenon took place. In the second example, VisIt was used to visualize 1 trillion particle data sets from the VPIC code, in combination with the H5Part and FastQuery systems. This allowed collaborators to explore energetic particle distribution, the formation of flux ropes and, and the alignment of the motion of energetic particles with the electric/magnetic fields.

3.3.1.2 ParaView (LANL, Kitware)

During the SDAV life-cycle, we had nine ParaView releases before the end of our project. There has been many major improvements in these releases. Some highlights include:

- Support for data parallel frameworks including Dax, Piston and vtkSMP. VTK-m, which unifies all of these technologies, will be included in ParaView 5.3.
- Development of a charting framework with support for symbol and equation rendering for annotation, and support for vector graphics output.
- Refactoring of the VTK and ParaView libraries to allow for the creation of smaller subsets of both frameworks. This was driven by the need to derive *in situ* ParaView libraries that fit the problem.
- Introduction of ParaView Catalyst, a ParaView based *in situ* library. Since its release, Catalyst have been integrated with DOE codes in many scientific domains, including Climate, CFD, Plasma, HEP, and Shock Physics.
- Numerous improvements to ParaView's visual analytics and quantitative analysis capabilities, including support for scatter plot matrices, parallel coordinates and histograms.
- Development of much improved ParaView and Catalyst User's Guides.
- Integration with ADIOS for post hoc IO as well as in transit visualization.
- Integration with DIY2 for the development of distributed algorithms.

We has six VTK major releases over the last 5 years. These releases included numerous improvements and new features in support of DOE needs, including ParaView and VisIt development. Highlights include a major rewrite of VTK's rendering engine to obtain large performance improvements (10x - 100x) on modern graphics cards and software rendering implementations, integration of OpenSWR for improved rendering on Intel Xeon Phi processors, integration with VTK-m, and major improvements to the VTK pipeline infrastructure for improved parallel processing.

We have collaborated with and supported various DOE science teams including

- VPIC: Kinetic plasma simulation, Bill Daughton, LANL, PI. Collaborations included post hoc visualization with ParaView and *in situ* analysis with Catalyst.
- HACC, Cosmology, Salman Habib, ANL, PI. Collaborations included post hoc visualization with ParaView, feature extraction and tracking algorithm development, *in situ* analysis with CosmoTools.
- Plasma Surface Interaction (PSI) SciDAC Application Partnership, visualizations of helium bubbles and tungsten cavities from LAMMPS simulations using VTK.

- MPAS: Climate simulation, post hoc and *in situ* analysis and visualization, algorithm development for feature tracking,
- CAM-SE: Climate simulation, post hoc analysis and visualization,
- OSCon - Optimizing SuperConductor Transport Properties through Large-Scale Simulation, SciDAC partnership with BES, deploying in ParaView a set of algorithms for extracting, tracking and visualizing vortex dynamics in large-scale time-dependent Ginzburg-Landau (TDGL) superconductor simulation data. We have also integrated IO functionality to load the simulation data into ParaView.

In conclusion, we have improved both the ParaView and VTK visualization tools in order to support new architecture features at the LCFs and similar machines. We also customized these tools according the specific needs of multiple scientific communities, helping them to achieve greatly improved efficiency, adding functionality they requested, and in several cases embedding our tools into their scientific frameworks. The collaboration with the VTK-m effort has been highly successful. Looking forward, as more algorithms are added to VTK-m to take advantage of multi-core and many many-core architectures, ParaView will automatically benefit from these new capabilities.

3.3.2 VTK - m Framework

3.3.2.1 VTK-m (Sandia, Kitware, ORNL, LLNL, UO)

When SDAV began in 2012, the scientific visualization community was just beginning to develop algorithms and software that run well on multi-core CPUs or many-core accelerators like GPUs. We identified 3 key projects addressing scientific visualization on multi/many-core processors: Piston, an ASC project lead by LANL, Dax, an ASCR project lead by SNL, and EAVL, an LDRD project lead by ORNL. SDAV adopted these products under its umbrella of tools.

Our evaluation of these tools revealed that each addressed a unique aspect of the problem. Piston focused on efficient and portable algorithms. Dax provided a top-down framework that simplified development. EAVL provided advanced data structures. Our initial work considered the integration of these tools. Although we did manage some forms of integration, the results were suboptimal. The integration was not tight enough to realize the full potential and ultimately we were in danger of repeating each other's code.

In response, we considered the feasibility of a tighter integration where the code was redesigned under a single software project. The plan required each software team to transfer their software technology to a new, unified project. Such consolidation of software is rare, but fortunately SDAV was structured to include as key personnel the PIs for each of these three projects. This gave us the motivation and organization to form a tight collaboration in which we all agreed to put aside our previous software and move to a new unified software base. Although much of the development of VTK-m was performed under a following ASCR project, this collaboration could never have formed without SDAV, and we consider this an important success of SDAV.

VTK-m version 1.0 was released June 7, 2016. This release includes the integration of the three predecessor toolkits, and with it we demonstrated an efficient combination of algorithm implementation, performance portability across devices, advanced data models, and high level scientific visualization building blocks [Mor2015b, Mor2016b]. More information about VTK-m is available on our web site (<http://m.vtk.org>).

During the run of SDAV we had two VTK-m code sprints: one in September 2015 at LLNL and one in August 2016 at Kitware. Among the two we had many participants that represented work from many different organizations including national laboratories (SNL, LANL, ORNL, LBNL, LLNL), universities (Oregon, UC Davis), and industry (Kitware, NVIDIA, Intelligent Light). These events allowed us to reach out to several interested developers to get them kick started with VTK-m development and also allowed us to make progress in several key areas of VTK-m and its algorithms.

VTK-m development continues to progress and is currently the only viable solution for DOE’s scientific visualization needs on multi- and many-core devices, and we expect much of future DOE research to contribute back to the VTK-m library. Furthermore, the DOE Exascale Computing Project (ECP) includes the development of several algorithms in VTK-m to replace the single threaded and MPI-only counterparts in VTK.

Next, we describe the progress of the three tools that were integrated into VTK-m: Piston, Dax, and EAVL.

3.3.2.2 Piston (LANL)

Early PISTON Algorithms. Our early work under the SDAV Institute focused on the development of visualization and analysis operators, such as isosurface, threshold, and cut surfaces, using portable, data-parallel “primitives” (e.g. scan, transform, and reduce). These algorithms were described and evaluated in our paper [Lo2012a], and have since been ported to VTK-m. The three projects which merged into VTK-m (PISTON, Dax, and EAVL) were described in the paper [Sew2012a], and their integration was presented in the papers [Chi2013a] and [Mor2016b].

In-Situ Data-Parallelism. As a precursor to the VTK-m / VTK integration, a ParaView plug-in was implemented for PISTON, and prototype in-situ adapters were developed using the Catalyst framework for several scientific codes, including the Vector Particle in Cell (VPIC) plasma simulation code, enabling them to execute our data-parallel visualization algorithms while the simulation is running.

Distributed Data Parallelism. While the VTK-m effort has been focused primarily on improving on-node, shared-memory performance, we also extended several data-parallel operators to run across nodes in distributed memory environments, and implemented algorithms such as isosurface and KD-tree construction using them. This approach was described in a paper [Sew2013a].

Cosmology Applications. Over the course of the SDAV project, we applied the data-parallel principles of PISTON and VTK-m to deliver new capabilities to the Hardware/Hybrid Accelerated Cosmology Code (HACC) in collaboration with the “Computation-Driven Discovery for the Dark Universe” SciDAC Application Partnership in High-Energy Physics (Salman Habib, PI). This work resulted in a number of publications highlighting both the visualization and analysis techniques used and the scientific results they enabled. [Sew2015a] presented the algorithmic details of our data-parallel, portable halo and halo center finding analysis operators. These operators enabled halo analysis to be performed on a half-trillion particle simulation run on 16,384 nodes of Titan. The results of this simulation, which was the first time that the concentration-mass relation has been measured from a single simulation volume over such an extended mass range, were published in [Hei2015a]. We developed innovative new workflows, which combine in-situ and off-line analysis, to deal with the large data generated by this simulation. These workflows were evaluated quantitatively in our Supercomputing paper [Sew2015b].

Topology / Feature Tracking. We have also collaborated with topologists to develop data-parallel algorithms. Our research work involved a general and flexible analysis environment which enables interactive exploration of feature evolution in time-varying data sets, regardless of the underlying data type. In order to demonstrate the generality of this framework, we have extended its applicability to several large-scale scientific and non-scientific data sets. For cosmology data, we implemented a data-parallel, friend-of-friends halo finding algorithm to construct a feature hierarchy for halos, and then tracked their evolution through time using our framework, the results of which was presented in the paper [Wid2014a]. In the case of plasma surface interaction data, we explored and analyzed the evolution of helium bubbles using our framework. We also visualized the evolution of pressure-perturbation events in weather data sets to assist the atmospheric scientists to better understand different weather phenomena. Finally, for healthcare data, we focused on exploring and analyzing patient progression over time utilizing a publically available intensive care unit (ICU) dataset. This work facilitated better predictions of patient outcomes, personalized medication, and more targeted interventions, and was published in the paper

[Wid2016a]. The groundwork in data-parallel topology laid by the SDAV project also led to the development of a data-parallel contour tree algorithm under separate funding, and the resulting paper, [Car2016a], was named Best Paper of the Large Data Analysis and Visualization Symposium in 2016.

3.3.2.3 Dax (Sandia)

Data Structure Adaptability. Much of the early SDAV work with Dax was in making sure its data structures were highly adaptable [Mor2012b]. The initial goal of this work was to improve the interface between Dax and the other multi-threaded libraries (PISTON and EAVL) as well as other established libraries (like VTK). This work was instrumental when combining the technologies from the three projects into a single software product (VTK-m).

Performance Under Layers of Abstraction. In addition to providing an abstract representation of a device (for device portability), Dax used several layers of abstraction to hide the complexities of parallel programming [Mor2012b]. These layers of abstraction worked by identifying common patterns in scientific visualization algorithm execution [Mor2013b]. This required several optimizations in the underlying framework. Of specific importance were geometry creation techniques [May2013a, Mil2014a].

Integration with Dynamic Libraries. The Dax library makes extreme use of C++ templates to maximize the efficiency of the algorithms. However, templates also require all types to be known at compile time, which is a problem when interfacing with a more dynamic software like VTK that uses virtual methods so that specific types do not need to be known until run time. As part of our work in integrating Dax with ParaView, we devised techniques to unroll possible types at run time to call into the appropriate template code.

Scanning Transmission Electron Microscopes (S/TEM). Dax was used to improve the processing in scanning transmission electron microscopes (S/TEM). This equipment generates large (1024^3 or greater) volumes that are often difficult to analyze. Dax was incorporated into TomViz (<http://tomviz.org/>), an open, general S/TEM visualization tool and provides streaming interactive contouring that significantly beats VTK's alternative algorithms.

3.3.2.4 EAVL (ORNL)

Advanced Data Structures. The EAVL focus was on a next generation data model [Mer2012a, Mer2012b]. Development under SDAV included support for quad-trees and higher order meshes in support of the scientific codes MADNESS and Chimera. The basic data model from EAVL has been ported to VTK-m, and we continue to refine this model.

In Situ Applications. One main use case of the EAVL library was its use as a lightweight visualization library to be used for *in situ* visualization in simulations. To ensure EAVL had minimal impact on simulations, mechanisms for zero-copy access to simulation host arrays were employed. Using zero-copy was often found to be 10x to 200,000x faster than conversion routines. EAVL also provided plotting, rendering, and annotation capabilities while less critical dependencies were trimmed (and compiling a base EAVL library with no dependencies was possible). Most of this functionality is transferred over to VTK-m.

We also experimented with and developed a set of light weight visualization plugins that are suitable for use in data staging environments. Our initial experiments consist of using EAVL and the ADIOS system. These were used to run the XGC-1 code on OLCF resources, staging the data to a set of nodes and then using visualization plugins developed in EAVL to perform basic data reductions and rendering operations of both field and particle data [Pug2014a, Kre2016a]. This work is being ported over to VTK-m [Pug2016c].

Rendering. EAVL received major rendering infrastructure improvements. This included an overhaul to support multiple renderers, in part to remove formerly mandatory rendering dependencies like OpenGL.

The new renderers include vector-based ones like Postscript/EPS, necessary for scientists to generate publication-quality one- and two-dimensional figures. These also include a ray tracing renderer with advanced lighting effects and an accurate direct volume renderer. These could be used with no extra software engineering burden in the form of third-part library dependencies, a critical feature for *in situ* use cases.

Effort was also spent exploring and implementing multi- and many-core accelerated versions of these advanced renderers, as particularly the raycasting and volume rendering ones are computationally intensive, and *in situ* use cases place higher performance demands on the visualization infrastructure. A major thrust of this exploration was to use common data-parallel primitives to accelerate these renderers [Lar2015a, Lar2015b]. These renderers are now available in VTK-m.

3.3.2.5 DIY: Block-Parallel Library (ANL, LBNL)

Over the 5 year SciDAC-3 period, we developed a new version of the DIY programming model which allows building other parallel analysis libraries on top of it. DIY is a programming model and runtime for block-parallel analytics on distributed-memory machines. Its main abstraction is block-structured data parallelism: data are decomposed into blocks; blocks are assigned to processors; computation is described over these blocks, and communication between blocks is defined by reusable patterns. One of the libraries that we built on DIY is Tess, to compute parallel Voronoi and Delaunay tessellations of particle datasets, a core part of the analysis of many simulated and measured datasets: N-body simulations, molecular dynamics codes, and LIDAR point clouds are just a few examples. However, the algorithms for computing these tessellations at scale perform poorly when the input data is unbalanced, such as the case in cosmological dark matter simulations. We investigated the use of k-d trees to evenly distribute points among processes. Because resulting point distributions no longer satisfy the assumptions of our earlier parallel Delaunay algorithm, we developed a new parallel algorithm that adapts to its input.

Our approach of using the k-d tree has led to very significant results. We evaluated the new algorithm using two late-stage cosmology datasets. The new running times are up to 50 times faster using the k-d tree compared with regular grid decomposition. Moreover, in the unbalanced data sets, decomposing the domain into a k-d tree is up to five times faster than decomposing it into a regular grid.

Our work resulted in three major publications and the release of two open-source software libraries. The article about DIY was published in the LDAH symposium collocated with IEEE Visualization 2016 [Mor2016a], and two articles about Tess were published in IEEE/ACM Supercomputing 2014 [Pet2014] and 2016 [Mor2016b]. Both the DIY and Tess software are available on Github.

Conclusion: *in situ* data processing requires scalable distributed-memory algorithms. Developing such algorithms is enabled with DIY's block-parallel programming model. Decomposing the domain into adaptive structures such as k-d trees allows irregular computations to be load-balanced. Libraries such as DIY and Tess are critical pieces of the distributed-memory algorithms in VTK-m, and we will continue to support the parallel communication needs of VTK-m in future research projects.

3.3.3 Flow Visualization Methods

3.3.3.1 Parallel Integral Curve System (UUtah)

Utah working in collaboration with SDAV partners at ORNL and LBNL expanded and hardened VisIt's Parallel Integral Curve System (PICS). The PICS code is an integral part of VisIt's analysis tools allowing researchers to analyze and visualize particles paths. As part of SDAV the PICS code was expanded to allow for the secondary analysis of the data produced by the system. The original system architecture was developed where the integral curves were the final output for either visualization (streamlines or path lines) or analysis (Poincaré maps).

However, with growing interest in Lagrange Coherent Structures (LCS) from DOE researchers in ocean, climate (ice flow), combustion, fusion, and other applications, there was a need to allow for the secondary analysis of the data produced. For instance, a common LCS analysis technique is to compute Finite Time Lyapunov Exponents (FTLE). These exponents are based on the eigenvalues computed using the initial integral curves. However, other structures are of interest, such as limit cycles and shrink and stretch lines which can be found by evaluating the associated eigenvectors. The analysis of the eigenvectors required additional infrastructure with the PICS code.

In addition to the infrastructure development the LCS operator has been expanded. As noted above, in addition to eigenvalues, eigenvectors or their combination are used for limit cycles and shrink and stretch lines all of which are part of LCS analysis. Finding limit cycles is an iterative search process that also utilizes the PICS system which was added as a new operator within VisIt. The Limit Cycle operator is separate from the LCS operator and can be used by any vector field. Finding shrink and stretch lines is based on local min/max FTLE values and was a new addition to the LCS operator. These min/max values are used as seed points along with the eigenvalues and are advected using the previously developed Integral Curve operator. All of the tools described have been deployed within VisIt and are currently being used by DOE and other researchers.

3.3.3.2 Uncertainty Flow Visualization (OSU)

Uncertainty Particle Tracing: We have developed several novel pathline tracing algorithms for time-varying flow data. As the size of simulations continues to increase, it is only possible to store a small subset of the time step data in order to save both storage space and analysis time. Computing pathlines from the reduced data sets, however, is susceptible to interpolation errors due to the lack of data. In this research, we developed a novel data reduction algorithm based on Bezier splines (a numerically stable method to represent curves) to increase the data accuracy, and a parametric error modeling with a least square fitting approach. Our pathline tracing algorithm utilizes the errors modeled by our approach where not only the uncertainty involved is quantified, but the accuracy of the resulting pathlines is also improved. This work was published in IEEE Pacific Visualization 2015 [Che2015a]. To ensure a clearer understanding of three-dimensional flow features, we have also developed a scalable algorithms for parallel stream surface generation [Lu2014a], and a novel domain decomposition algorithm that allows large scale parallel computation of streamlines [Bis2016a]. Our work on uncertainty particle tracing and visualization of uncertain flow features have been used and evaluated by ANL climate scientists Scott M. Collis and Jonathan J. Helmus. The in situ detection of flow features will have a wide applications on DOE's large scale flow simulations such as detecting magnetic flux vortices in superconductor simulations done at ANL.

In Situ Visualization and Analysis of Flow: We have developed several novel techniques for *in situ* identification of salient flow features. With recent advancements of high performance computing, high-resolution unsteady flow fields allow in depth exploration of turbulence and its possible causes. Performing turbulence analysis, however, involves significant effort to process large amounts of simulation data, especially when investigating abnormalities across many time steps. In order to assist scientists during the exploration process, we created a visual analytics framework to identify suspected spatiotemporal flow abnormality through a comparative visualization so that scientists are able to focus on relevant data in more detail. To achieve this, we developed efficient analysis algorithms derived from domain knowledge and convey the analysis results through juxtaposed interactive plots. Using our integrated visualization system, scientists can visually investigate the detected regions for potential candidate features and further explore their associated spatial regions to enhance the understanding of this phenomenon. Positive feedback from scientists demonstrate the efficacy of our system in analyzing jet engine rotating stall. This work was published in IEEE SciVis 2015 and a special issue of IEEE Transactions on Visualization and Computer Graphics [Che2015b]. Our work also won the best paper honorable mention in IEEE SciVis 2016 [Dut2016a]

3.3.3.3 Flow Visualization on GPUs (LBNL)

Within the context of scaling flow visualization methods, the key component of which is a parallel computation of integral curves, we have focused on a pair of related objectives that aim to produce software methods for flow visualization that are of high quality, in production use by the science community, and that are suitable for use on both multi-core CPU and many-core GPU platforms.

Scaling flow visualization methods is a challenge since the method's parallel performance is dependent upon several factors: the placement/density/number of seed points (an input parameter), the characteristics of the underlying vector field through which curves are computed (input data dependency), and various factors related to the computational architecture (faster vs. slower cores, faster vs. slower memory, the mechanisms and cost of moving data/memory, and so forth).

Our efforts have focused on fostering a better understanding of flow visualization performance on various platforms, and under varying workload conditions [Chi2014b]. For workloads that are heavy in computation, such as high particle density with small integration steps, GPU-based platforms tend to perform better. In contrast, workloads that have lower particle density and larger integration steps, which place a higher load on data movement, tend to perform better on multi-core CPU platforms and on systems with better interconnect fabric. However, CPU-based platforms with high core density and good interconnect fabric proved to be competitive with GPU platforms across diverse workloads.

In the longer term, this type of work can inform how software infrastructure for flow visualization, such as VisIt and VTK-m, can take advantage of different architectures to service varying workloads in a post-processing configuration. Such adaptivity would be the subject of future work.

3.3.4 Rendering

3.3.4.1 Advanced Volume Rendering in VisIt (UUtah)

Over the last five years, we developed a number of techniques to improve the GPU-based volume rendering in VisIt through the SLIVR rendering path. We extended VisIt to include a scalable volume rendering solution that produces similar quality images to the enhanced GPU volume rendering. These improvements are part of the VisIt release. As the programming model of modern supercomputers switches from pure MPI to MPI for inter-node communication, and shared memory and threads for intra-node communication, the bottleneck in most systems is no longer computation but communication between nodes. The Task Overlapped Direct send Tree, TOD-Tree, is a new compositing algorithm for Hybrid/MPI parallelism that minimizes communication and focuses on overlapping communication with computation. We have extended the TOD-Tree compositing method to take advantage of GPU-Direct for GPU-enabled computing resources. TOD-Tree has three stages: a direct send stage where nodes are arranged in groups and exchange regions of an image, followed by a tree compositing stage and a gather stage. We have worked closely with NVIDIA to utilize the direct GPU-MPI remote data copy mechanism, GPU-Direct, to perform compositing completely on the GPU nodes. This avoids copying data between the CPU and the GPU. We published and presented a paper at 2015 EuroGraphics Parallel Graphics and Visualization [Gro2015a].

3.3.4.2 High-End Volume Visualization (UCD)

Volume rendering is a powerful tool for visualizing complex 3D flow field. We aim to enhance the usability of volume visualization by improving both interactivity and rendering quality. To enhance the perception of complex flow structures and features, we have studied different aspects of volume rendering. For example, we have developed more scalable rendering of AMR data, presented at the 2013 LDAV Symposium (receiving the best paper award) [Lea2013a], as well as hybrid grid volume data and geodesic grid data, both presented at the 2014 LDAV Symposium [Shi2014a, Xie2014a]. These have numerous applications to many SciDAC research areas including climate modeling, fusion simulations,

and astrophysics simulations. We have also been working on advanced illumination techniques for interactive volume visualization that incorporates the more physical light propagation, absorption, and scattering within the volumetric medium to more accurately present 3D structure and spatial relationships. Papers describing this work was published in ACM SIGGRAPH and IEEE Transactions on Visualization and Computer Graphics [Zha2013b and Zha2013c]. All these advancements benefit demanding 3D visualization tasks commonly found in SciDAC applications.

Unstructured grids are increasingly used by large-scale simulations, and a few rendering algorithms have been developed by us and others for visualizing unstructured-grid volume data. However, while the benefits of using advanced illumination models in volume visualization have been previously demonstrated, interactive rendering has only been achieved for regular-grid volume data. In this SciDAC project, we have developed an advanced illumination method specifically for interactive visualization of 3D unstructured-grid data. The basis of the design is a partial differential equation based illumination model to simulate the light propagation, absorption, and scattering. In particular, a two-level scheme is introduced to overcome the challenges presented by unstructured grids. Our extensive experimental studies show that the added illumination effects such as global shadowing and multiple scattering not only lead to a more visually pleasing visualization, but also greatly enhance the perception of the depth information and complex spatial relationships for features of interest in 3D flow field data. This 3D visualization enhancement is timely as unstructured grids are becoming increasingly popular for a variety of scientific simulation applications in the SciDAC community. A paper reporting this work was presented at PacificVis 2015 [Shi2015a].

In this project period, Min Shih, a PhD student at UCD, over a summer internship successfully incorporated an advanced illumination design into a production visualization system at the Argonne National Laboratory. Future directions will include expanding the performance and quality of these advanced rendering techniques as well as continued implementation into new application areas.

3.3.4.3 Parallel Particle Rendering and Volume Rendering with v13 (ANL)

v13 is a parallel framework for large-scale data visualization and analysis developed at Argonne National Laboratory. Its design is modular to facilitate the development and testing of new algorithms and methods, as well as deploying it on varied hardware platforms. v13 was originally conceived as a parallel hardware-accelerated solution for ray casting volume rendering of regular grids [Riz2014a].

Under the umbrella of SDAV, v13 evolved in multiple aspects. Firstly, its data reader and rendering modules were extended to support visualization of AMR datasets [Lea2013a]. This work received a Best Paper Award at the 3rd IEEE Symposium on Large Data Analysis and Visualization (LDAV), 2013. Another significant contribution was the addition of hardware accelerated rendering of point sprites for large-scale particle data sets [Riz2014b, Riz2015a]. The new point sprite rendering capabilities, along with the existing large-scale ray casting volume rendering algorithm, allowed the ALCF visualization team to deliver production-quality visualizations for INCITE projects, including “Parameter Studies of Boussinesq Flows”, PI Susan Kurien, and “Cosmological Simulations for Large-Scale Sky Surveys”, PI Salman Habib [Hei2014a, Hei2015a].

In addition, v13 was successfully coupled to the LAMMPS molecular simulation code for *in situ* visualization of large-scale atomistic data [Riz2015b, Riz2016a]. We also focused on improving image quality of the volume rendering module, developing an algorithm for efficient distributed global illumination based on voxel cone tracing [Shi2016a], which received an Honorable Mention Award at LDAV 2016. Furthermore, we used v13 as a modular framework to explore novel remote RAM technologies, demonstrating that it is possible to access a large pool of remote memory achieving more than 75% of peak network bandwidth with low latencies [Zaw2016a]. Finally, important improvements were also made to the mechanism for interactive streaming from v13 running on a visualization cluster to large tiled displays [Jia2015a], which received the Best Poster Award at LDAV 2015.

3.3.5 Ensembles, Uncertainty

3.3.5.1 Ensemble-vis (UUtah)

University of Utah, working with SDAV partners at ORNL and LLNL, developed prototype tools for ensemble analysis and visualization within the VisIt framework. These tools did not move beyond the prototype stage because they required major infrastructure changes within VisIt that were not feasible given the resources. These infrastructure changes would have made ensembles first class data objects with VisIt. That is, an ensemble data set would have been treated exactly like a single data set within VisIt's execution pipeline. Instead, python scripts and tools were developed that automatically handled the integration of ensemble data sets that were then reduced into a single data set that fit within VisIt's execution pipeline.

One of the tools developed allowed for collating ensembles of data and expanded VisIt's cross mesh field evaluations (CMFE) to ensemble data sets. Using the CMFE combined with VisIt's powerful expression mechanism gave users a way to collate data in a variety ways on a per time step basis. The collating of ensemble data is a critical step because the modeling is rarely a linear function of the data, that is $\text{sum}(f(x)) \neq f(\text{sum}(x))$. For the modeling, a new operator, "Statistical Trends" was deployed in VisIt that allows for a user to apply different statistical functions to look for trends in data over time. The operator complemented the abilities of the CMFE operator as the users could collate on either per time step basis or over multiple time steps. Both operators implemented basic statistic functions (min, max, mean, variance, slope, residuals). Though these tools had to be used with python scripting within VisIt they were successfully used to analyze CMIP-5 climate data and are currently being used by DOE and other researchers.

3.3.5.2 Determining Uncertainty in Ensemble Simulations (UCD)

We have worked in conjunction with Lawrence Berkeley National Laboratory climate researchers and Pacific Northwest National Laboratory groundwater researchers to develop techniques to measure the modality of the distributions that arise from ensemble simulations, and have developed methods that can be used to visualize "trends" in such simulations. These methods are based upon a known statistical test – Hardigan's Dip Test – but are modified to garner more information from the field. Furthermore, we have developed a new method for determining the uncertainty in the models by comparing each ensemble to a Bayesian Model Average. By using ground-truth data we can calculate the Bayesian Model Average, and compare the ensembles to this average [Gos2013a]. These methods have the potential to assist in analyzing the copious amounts of data that comes from ensemble simulations and can determine where the simulation outputs produce viable distributions, and where they don't. We have utilized these results to support climate simulations as well as groundwater simulations of uranium seepage in Rifle Colorado. Much of this work was published in IEEE Transactions on Visualization and Computer Graphics [Ben2016a, Obe2016a].

4 Committees

4.1 Software Infrastructure

The role of SDAV's Software Infrastructure Committee (SIC) was to inform and aid in the design of infrastructure that allows different technologies to interoperate. The committee drew on experts from the SDAV Institute to perform integration and interoperability tasks, and they coordinated with SDAV's Executive Council on decisions as needed. The technologies used by SDAV already had existing software engineering practices, which eased the responsibilities of the SIC, since good practices were already being applied.

SIC activities included releases of software, integration of software, and inventories. In terms of software

releases, SDAV software saw many releases over the past five years, including dozens of releases of parallel visualization tools (ParaView, VisIt), I/O Frameworks and monitoring tools (ADIOS, PnetCDF, ROMIO, GLEAN, Darshan), indexing and code coupling tools (FastBit, DataSpaces), and data analysis Frameworks and tools (PIDX, ViSUS, MSCEER, TALASS, NDDAV) among other software packages. These software releases included rigorous testing and integration with SciDAC applications and their data.

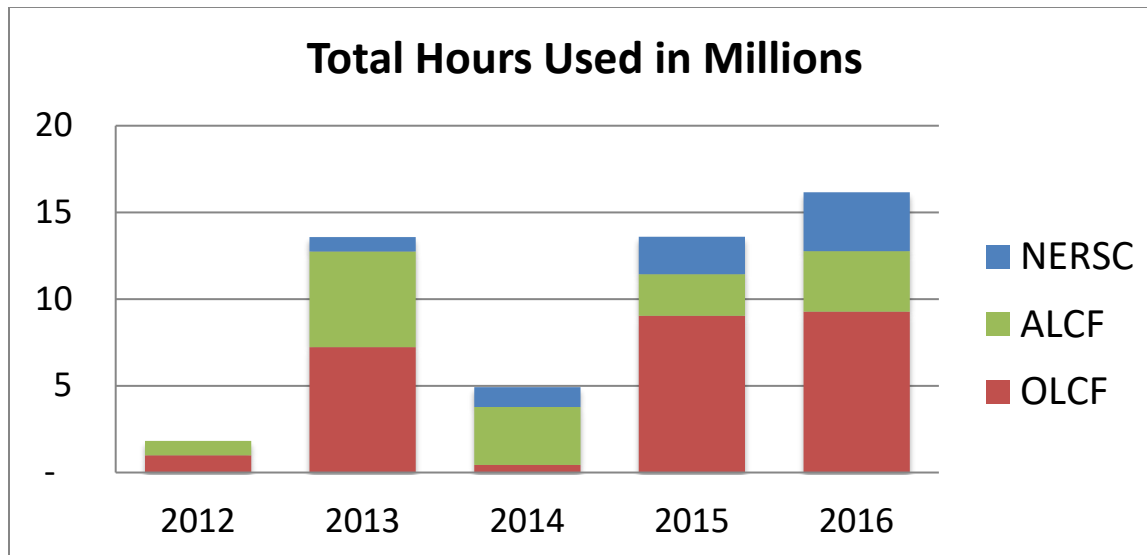
SDAV led the way for integration of many of our software technologies. For example, VisIt and Paraview were both integrated with ADIOS, and researchers in the fusion EPSI project were able to use this to enable their large-scale science. Similarly, ParaView and PISTON were integrated, and this enabled climate applications to understand and visualize their large scale data. Finally, VisIt and EAVL, one of the core components of VTK-m were integrated, and this led into our project creating visualization services that were used in several fusion SciDAC projects.

The SIC took inventory of all SDAV software on behalf of the SDAV EC, so that SDAV stakeholders could better understand the SDAV portfolio, as well as each package's role and maturity. The SIC also prepared materials for DOE's Institute-wide inventory, reporting on information for DBScan, FastBit, FastQuery, DataSpaces, Darshan, Dax, ImageVis3D, VTK, ParaView, Catalyst, DIY, VisIt, PIDX, ViSUS, PISTON, MSCEER, GLEAN, TALASS, NDDAV, HDF5, and UltraVis-P. Our inventory was cataloged on the SDAV web page, each pointing to user guides, download instructions, usage examples, etc., enabling potential customers to become familiar with our software projects.

Many people in SDAV also saw the need for many-core visualization libraries, which are necessary for applications running on the LCFs and NERSC. In the first two years of SDAV, the compatibility and future of DAX, EAVL, and PISTON was an open question. Ultimately, these packages merged into a new package, VTK-m, which is being directly integrated into VisIt, and will be integrated into ParaView via a VTK wrapper. This has been a major outcome from SDAV, and VTK-m has emerged in a manner consistent with SIC goals, including paths for interoperability with other packages, and excellent software engineering practices.

4.2 Facilities Deployment

The Facilities Committee has been tasked with providing the SDAV Institute with access to computing cycles at DOE Supercomputing centers and ensuring that SDAV software is installed and available to the user community. To provide SDAV members with access at the computing facilities we have focused on writing proposals to the LCFs at ANL and ORNL, and to NERSC for allocations on each of the systems. Over the 5-year period of SDAV we have secured a total of 41.7 million hours across the three centers. These allocations have been oversubscribed to a total usage of 50.1 million hours. The chart below summarizes the resources used across the three centers over the 5-year period. As can be seen in the chart, the drop in hours used in 2014 was primarily because of a drop in usage at OLCF due to delays encountered in securing a renewal for the allocation awarded in 2013. As shown in subsequent years, the committee worked to increase resource availability for the remainder of the project.



These allocations have provided critical resources for the deployment and testing of SDAV software. These include VisIt, ParaView, Darshan, ADIOS, DataSpaces, DIMES, Flexpath, PIDX, ALACRITY, Fastbit, VTK, VTK-m, and others. In addition, these allocations have been used for algorithm development and scaling studies across a broad range of core SDAV areas, including feature tracking and detection; flow visualization; *in situ* visualization; data indexing and querying. There have been significant interactions with several ASCR and INCITE projects, including EXaCT, EPSI, to name a few.

These allocations have been instrumental in a large number of publications, across a wide range of topics. Selected publications include: flow visualization [Ran2016c, Pug2016b, Che2015a, Lu2015a, Lu2014a, Wan2013a, Yuc2013a, Car2013a, Lin2013a, Cam2012a, Nou2012a], *in situ* analysis and visualization [Lar2016a, Pug2016c, Ye2015a, Gam2013a, Wan2013a, Ben2012a], queries [Lu2015a, Byn2013a, Lin2013a, Byn2012b], visualization tools [Shi2016a, Riz2016a, Zaw2016a], feature detection and tracking [Per2016a], I/O and workflows [Lof2016a, Kum2014b, Kum2014a, Boy2014a, Car2013a, Kum2013a, Liu2013a, Ben2012a]. A number of publications from this list have been honored as best paper winners and finalists at conferences.

The deployment of SDAV at the LCFs and NERSC is illustrated in the table below. As noted in the legend, software is available in one of three ways. Software that is installed and supported as a stand-alone package are shown in red. Software that is part of other supported tools are shown in green. Finally, software that is locally installed, but unsupported by the center, or is part a private tool or applications are shown in blue. Additionally, information about all SDAV supported software is available on the SDAV website: <http://sdav-scidac.org/toolkit.html>.

Software	ALCF	NERSC	OLCF	Software	ALCF	NERSC	OLCF
ADIOS				OSUFlow			
CEDMAV				ParaView			
DataSpaces				PNetCDF			
Darshan				PIDX			
DIY				UCDVis			
GLEAN				VisIt			
Fastbit				ViSUS			
FastQuery				VTK			
Flexpath				VTK-m			
IceT				WarpIV			

█ Installed
█ Installed in other tools
█ Local, unsupported

4.3 Outreach Activities

Since the SDAV award we have excelled with community outreach and impact of SDAV research and software. We have maintained updated internal and external SDAV websites, which are used for internal communication as well as a public facing site (sdav-scidac.org). The public website consists of general information about the institute, with the majority of the content being driven by research highlights, the SDAV software toolkit, and publications. The SDAV Toolkit (sdav-scidac.org/toolkit.html) is a gateway to useful software and code-based resources that have been developed through SDAV members.

Because of SDAV’s high quality research, SDAV PIs were invited to give more than 35 Keynote and Plenary Presentations at international research conferences and workshops including the ACM Symposium on High-Performance Parallel and Distributed Computing, SIAM Annual Conference, Eurographics Symposium on Parallel Graphics and Visualization, the International Parallel and Distributed Processing Symposium, and XSEDE. Additionally, SDAV PIs gave more than 160 invited presentations at conferences and workshops.

SDAV PIs have played leading roles in the organization of more than 45 research conferences and workshops, including the IEEE Symposium on Large Data Analysis and Visualization (LDAV) held in conjunction with the IEEE Visualization Conference, the Ultra-Scale Visualization Workshop, Workshop on Petascale Data Analytics: Challenges and Opportunities and the Parallel Data Storage Workshop held multiple times in conjunction with SuperComputing conferences. All of these meetings brought together computational scientists, data management and visualization researchers and practitioners, and industry and fostered greater exchange between them. In addition, SDAV PIs served on hundreds of conference and workshop program and paper committees.

In addition to publishing 451 papers, SDAV members gave more than 80 tutorials on SDAV software, which included several well attended tutorials on VisIt, ParaView, ADIOS, Darshan, Romio, Piston, DAX, and EAVL. These tutorials were given in well-established conferences such as SuperComputing, and several visualization conferences.

Finally, because of their respect in the research community, SDAV PIs have been chosen to serve on multiple national and international advisory boards.

5 Appendix: Publications over the 5-year period

2017

1. [Lat2017a] Rob Latham, Matthieu Dorier, Robert Ross. **“Get out of the way! Applying compression to internal data structures,”** In *Pdsw-discs 2016: 1st joint international workshop on parallel data storage & data intensive scalable computing systems*, held in conjunction with SC2016, 2017.
2. [Wid2017a] W. Widanagamaachchi, A. Jacques, B. Wang, E. Crosman, P.-T. Bremer, V. Pascucci, J Horel. **“Exploring the Evolution of Pressure-Perturbations to Understand Atmospheric Phenomena,”** In *IEEE Pacific Visualization Symposium (PacificVis)* , 2017.

2016

3. [Bau2016a] Andrew C. Bauer, Hasan Abbasi, James Ahrens, Hank Childs, Berk Geveci, Scott Klasky, Kenneth Moreland, Patrick O’Leary, Venkatram Vishwanath, Brad Whitlock, E. Wes Bethel. **“In Situ Methods, Infrastructures, and Applications on High Performance Computing Platforms,”** In *Computer Graphics Forum*, Vol. 32, No. 3, pp. 577--597. June, 2016.
DOI: [10.1111/cgf.12930](https://doi.org/10.1111/cgf.12930)
4. [Ben2016a] Kevin Bensema, Luke J. Gosink, Harald Obermaier, Kenneth I. Joy. **“Modality-Driven Classification and Visualization of Ensemble Variance,”** In *IEEE Transactions on Visualization and Computer Graphics*, Vol. 22, No. 10, 2016.
5. [Bha2016a] Harsh Bhatia, Attila G. Gyulassy, Valerio Pascucci, Martina Bremer, Mitchell T. Ong, Vincenzo Lordi, Erik W. Draeger, John E. Pask, & Peer-Timo Bremer. **“Interactive Exploration of Atomic Trajectories Through Relative-Angle Distribution and Associated Uncertainties,”** In *2016 IEEE Pacific Visualization Symposium (PacificVis)*, pp. 120-127. April, 2016.
6. [Bis2016a] Biswas, Ayan; Strelitz, Richard; Woodring, Jonathan; Chen, Chun-Ming; Shen, Han-Wei. **“A Scalable Streamline Generation Algorithm Via Flux-Based Isocontour Extraction,”** In *Eurographics Symposium on Parallel Graphics and Visualization (EGPGV16)*, June, 2016.
7. [Boz2016a] Ebru Bozdag Daniel Peter Matthieu Lefebvre Dimitri Komatitsch Jeroen Tromp Judith Hill Norbert Podhorszki David Pugmire. **“Global adjoint tomography: first-generation model,”** In *Geophysical Journal International*, Vol. 207, No. 3, Oxford University Press, pp. 1739-1766. Dec, 2016.
DOI: [10.1093/gji/ggw356](https://doi.org/10.1093/gji/ggw356)
8. [Bre2016a] P.-T. Bremer, A. Gruber, J. Bennett, A. Gyulassy, H. Kolla, J. Chen, R.W. Grout. **“Identifying turbulent structures through topological segmentation,”** In *Com. in App. Math. and Comp. Sci.*, Vol. 11, No. 1, pp. 37-53. 2016.
9. [Bre2016b] P.-T. Bremer. **“ADAPT - Adaptive Thresholds for Feature Extraction,”** In *Topology-Based Methods in Visualization*, Springer, 2016.
10. [Car2016a] Hamish Carr, Gunther Weber, Christopher Sewell, James Ahrens. **“Parallel Peak Pruning for Scalable SMP Contour Tree Computation,”** In *Proceedings of the IEEE Symposium on Large Data Analysis and Visualization (LDAV)*, Baltimore, Maryland, Note: *Best Paper Award. The results reported in this paper stem from the PISTON / VTK-m work established by SDAV; the specific work for this paper was funded under the ASCR XVIS project.*, October, 2016.
11. [Che2016a] Chen, Chun-Ming, Dutta, Soumya, liu, Xiaotong, Heinlein, Gregory, Shen, Han-Wei, Chen, Jen-Ping. **“Visualization and Analysis of Rotating Stall for Transonic Jet Engine**

- Simulation,**” In *IEEE SciVis 2015, also in IEEE Transactions on Visualization and Computer Graphics (TVCG)*, vol. 22, no. 1, 2016.
12. [Cho2016a] Jong Youl Choi, Tahsin Kurc, Jeremy Logan, Matthew Wolf, Eric Suchyta, James Kress, David Pugmire, Norbert Podhorszki, Eun-Kyu Byun, Mark Ainsworth, Manish Parashar, Scott Klasky. **“Stream processing for near real-time scientific data analysis,”** In *Scientific Data Summit (NYSDS)*, IEEE Xplore, *IEEE*, pp. 1-8. August, 2016.
DOI: [10.1109/NYSDS.2016.7747804](https://doi.org/10.1109/NYSDS.2016.7747804)
 13. [Dev2016a] Dharshi Devendran, Suren Byna, Bin Dong, Brian van Straalen, Hans Johansen, Noel Keen, Nagiza Samatova. **“Collective I/O Optimizations for Adaptive Mesh Refinement Data Writes on Lustre File System,”** In *Cray User Group (CUG)*, May, 2016.
 14. [Don2016a] Bin Dong, Suren Byna, Kesheng Wu. **“SDS-Sort: Scalable Dynamic Skew-aware Parallel Sorting,”** In *The ACM International Symposium on High-Performance Parallel and Distributed Computing (HPDC)*, July, 2016.
 15. [Dut2016a] Dutta, Soumya, Shen, Han-Wei. **“Distribution Driven Extraction and Tracking of Features for Time-varying Data Analysis,”** In *IEEE SciVIS 2015, also in IEEE Transactions on Visualization and Computer Graphics*, vol. 22, no. 1, 2016.
 16. [Han2016a] Dianwei Han, Ankit Agrawal, Wei-keng Liao, Alok Choudhary. **“A Novel Scalable DBSCAN Algorithm with Spark,”** In *the 5th International Workshop on Parallel and Distributed Computing for Large Scale Machine Learning and Big Data Analytics, held in conjunction with the International Parallel & Distributed Processing Symposium*, Chicago, May, 2016.
 17. [Hsu2016a] Chien-Hsin Hsueh, Jacqueline Chu, Kwan-Liu Ma, Joyce Ma, Jennifer Frazier. **“Fostering Comparisons: Designing an Interactive Exhibit that Visualizes Marine Animal Behaviors,”** In *Proceedings of PacificVis 2016 (to appear)*, 2016.
 18. [Kan2016a] Qiao Kang, Wei-keng Liao, Ankit Agrawal, Alok Choudhary. **“A Filtering-based Clustering Algorithm for Improving Spatio-temporal Kriging Interpolation Accuracy,”** In *the 25th ACM International Conference on Information and Knowledge Management*, Indianapolis, Indiana, October, 2016.
 19. [Kre2016a] James Kress, Randy Michael Churchill, Scott Klasky, Mark Kim, Hank Childs, David Pugmire. **“Preparing for In Situ Processing on Upcoming Leading-edge Supercomputers,”** In *Supercomputing Frontiers and Innovations*, Vol. 3, No. 4, pp. 49-65. 2016.
DOI: [10.14529/jsfi160404](https://doi.org/10.14529/jsfi160404)
 20. [Kre2016b] James Kress David Pugmire Scott Klasky Hank Childs. **“Visualization and analysis requirements for in situ processing for a large-scale fusion simulation code,”** In *ISAV '16 Proceedings of the 2nd Workshop on In Situ Infrastructures for Enabling Extreme-scale Analysis and Visualization*, pp. 45-50. 2016.
DOI: [10.1109/ISAV.2016.14](https://doi.org/10.1109/ISAV.2016.14)
 21. [Lar2016a] Larsen, Matthew, Harrison, Cyrus, Kress, James, Pugmire, David, Meredith, Jeremy S., Childs, Hank. **“Performance Modeling of In Situ Rendering,”** In *Proceedings of the International Conference for High Performance Computing, Networking, Storage and Analysis (SC16)*, Salt Lake City, Utah, pp. 24:1--24:12. Nov, 2016.
ISBN: [978-1-4673-8815-3](https://doi.org/978-1-4673-8815-3)
 22. [Lar2016b] Matthew Larsen, Kenneth Moreland, Chris R. Johnson, Hank Childs. **“Optimizing Multi-Image Sort-Last Parallel Rendering,”** In *Proceedings of IEEE Symposium on Large Data Analysis and Visualization (LDAV)*, Baltimore, MD pp. 37--46. Oct, 2016.
 23. [Lee2016a] Sunwoo Lee, Wei-keng Liao, Ankit Agrawal, Nikos Hardavellas, Alok Choudhary. **“Evaluation of K-Means Data Clustering Algorithm on Intel Xeon Phi,”** In *the Workshop on*

Advances in Software and Hardware for Big Data to Knowledge Discovery, held in conjunction with the IEEE Bigdata Conference, Washington, D.C., December, 2016.

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25. [Liu2016b] S. Liu, P.-T. Bremer, J. Thiagarajan, B. Wang, B. Summa, V. Pascucci. **“Grassmannian Atlas: A General Framework for Exploring Linear Projections of High-Dimensional Data. Shusen Liu,”** In *Comput. Graph. Forum*, 2016.
26. [Mal2016a] Dan Maljovec, Bei Wang, Paul Rosen, Andrea Alfonsi, Giovanni Pastore, Cristian Rabiti, Valerio Pascucci. **“Rethinking Sensitivity Analysis of Nuclear Simulations with Topology,”** In *IEEE Pacific Visualization Symposium (PacificVis)*, pp. 64-71. April, 2016.
DOI: [10.1109/PACIFICVIS.2016.7465252](https://doi.org/10.1109/PACIFICVIS.2016.7465252)
27. [Moo2016a] Changsung Moon, Dakota Medd, Paul Jones, Steve Harenberg, William Oxbury, Nagiza F. Samatova. **“Online Prediction of User Actions through an Ensemble Vote from Vector Representation and Frequency Analysis Models,”** In *SIAM International Conference on Data Mining (SDM)*, May, 2016.
28. [Mor2016a] Kenneth Moreland. **“The Tensions of In Situ Visualization,”** In *IEEE Computer Graphics and Applications*, Vol. 36, No. 2, pp. 5-9. March/April, 2016.
DOI: [10.1109/MCG.2016.35](https://doi.org/10.1109/MCG.2016.35)
29. [Mor2016b] Kenneth Moreland, Christopher Sewell, William Usher, Li-ta Lo, Jeremy Meredith, David Pugmire, James Kress, Hendrik Schroots, Kwan-Liu Ma, Hank Childs, Matthew Larsen, Chun-Ming Chen, Robert Maynard, Berk Geveci. **“VTK-m: Accelerating the Visualization Toolkit for Massively Threaded Architectures,”** In *IEEE Computer Graphics and Applications*, Vol. 36, No. 3, pp. 48--58. May/June, 2016.
DOI: [10.1109/MCG.2016.48](https://doi.org/10.1109/MCG.2016.48)
30. [Mor2016c] Kenneth Moreland. **“Why We Use Bad Color Maps and What You Can Do About It,”** In *Proceedings of Human Vision and Electronic Imaging (HVEI)*, February, 2016.
DOI: [10.2352/ISSN.2470-1173.2016.16.HVEI-133](https://doi.org/10.2352/ISSN.2470-1173.2016.16.HVEI-133)
31. [Mue2016a] Chris Muelder, Biao Zhu, Wei Chen, Hongxin Zhang, Kwan-Liu Ma. **“Visual Analysis of Cloud Computing Performance Using Behavioral Lines,”** In *Proceedings of PacificVis 2016 (to appear)*, 2016.
32. [Neu2016a] Tyson Neuroth, Franz Sauer, Weixing Wang, Stephane Ethier, Choong-Seock Chang,, Kwan-Liu Ma. **“Scalable Visualization of Time-varying Multi-parameter Distributions Using Spatially Organized Histograms,”** In *IEEE Transactions on Visualization and Computer Graphics*, Vol. PP, No. 99, 2016.
33. [Obe2016a] Harald Obermaier, Kevin Bensema, Kenneth I. Joy. **“Visual Trends Analysis in Time-Varying Ensembles,”** In *IEEE Transactions on Visualization and Computer Graphics*, Vol. 22, No. 10, 2016.
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36. [Pre2016a] Annie Preston, Ramyar Ghods, Jinrong Xie, Franz Sauer, Nick Leaf, Kwan-Liu Ma, Esteban Rangel, Eve Kovacs, Katrin Heitmann, Salman Habib. **“An Integrated Visualization System for Interactive Analysis of Large, Heterogeneous Cosmology Data,”** In *Proceedings of PacificVis 2016 (to appear)*, 2016.
37. [Pug2016a] David Pugmire; James Kress; Hank Childs; Matthew Wolf; Greg Eisenhauer; Randy Churchill; Tahsin Kurc; Jong Choi; Scott Klasky; Kesheng Wu; Alex Sim; Junmin Gu. **“Visualization and Analysis for Near-Real-Time Decision Making in Distributed Workflows,”** In *High Performance Data Analysis and Visualization (HPDAV) 2016 held in conjunction with IPDPS 2016*, Chicago, May, 2016.
38. [Pug2016b] Roberto Sisneros, David Pugmire. **“Tuned to Terrible: A Study of Parallel Particle Advection State of the Practice.,”** In *High Performance Data Analysis and Visualization (HPDAV) 2016 held in conjunction with IPDPS 2016*, Chicago, May, 2016.
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42. [Ran2016c] Esteban Rangel, Nan Li, Salman Habib, Tom Peterka, Ankit Agrawal, Wei-Keng Liao, Alok Choudhary. **“Parallel DTFE Surface Density Field Reconstruction,”** In *the IEEE International Conference on Cluster Computing*, Taipei, Taiwan, Note: *Best paper award*, September, 2016.
43. [Riz2016a] Silvio Rizzi, Mark Hereld, Joseph A. Insley, Preeti Malakar, Michael E. Papka, Thomas Uram, Venkatram Vishwanath. **“Coupling LAMMPS and the v13 Framework for Co-Visualization of Atomistic Simulations,”** In *High Performance Data Analysis and Visualization (HPDAV) 2016*, May, 2016.
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45. [Rub2016a] Oliver Ruebel, Burlen Loring, Jean-Luc Vay, David P. Grote, Remi Lehe, Stepan Bulanov, Henri Vincenti., E. Wes Bethel. **“WarpIV: In Situ Visualization and Analysis of Ion Accelerator Simulations,”** In *IEEE Computer Graphics and Applications*, Vol. 36, No. 3, pp. 22-35. may, 2016.
ISSN: 0272-1716
DOI: [10.1109/MCG.2016.62](https://doi.org/10.1109/MCG.2016.62)
46. [Rud2016a] U. Rde, K. Willcox, L. C. McInnes, H. De Sterck, G. Biros, H. Bungartz, J. Coronas, E. Cramer, J. Crowley, O. Ghattas, M. Gunzburger, M. Hanke, R. Harrison, M. Heroux, J. Hesthaven, P. Jimack, C. Johnson, K. E. Jordan, D. E. Keyes, R. Krause, V. Kumar, S. Mayer, J. Meza, K. M. Mrken, J. T. Oden, L. Petzold, P. Raghavan, S. M. Shontz, A. Trefethen, P. Turner, V. Voevodin, B. Wohlmuth, C. S. Woodward. **“Research and Education in Computational Science and Engineering,”** Subtitled **“Report from a workshop sponsored by the Society for Industrial and**

- Applied Mathematics (SIAM) and the European Exascale Software Initiative (EESI-2),”** Aug, 2016.
47. [Sau2016a] Franz Sauer, Yubo Zhang, Weixing Wang, Stephane Ethier, Kwan-Liu Ma. **“Visualization Techniques for Studying Large-Scale Flow Fields from Fusion Simulations,”** In *Computer Science and Engineering*, Vol. 18, No. 2, IEEE, pp. 68-77. March, 2016.
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 51. [Ste2016a] H. De Sterck, C. Johnson, L. C. McInnes. **“Special Section on Two Themes: CSE Software and Big Data in CSE,”** In *SIAM J. Sci. Comput*, Vol. 38, No. 5, SIAM, pp. S1--S2. 2016.
 52. [Sun2016a] Qian Sun, Melissa Romanus, Tong Jin, Hongfeng Yu, Peer-Timo Bremer, Steve Petruzza, Scott Klasky, Manish Parashar. **“In-Staging Data Placement for Asynchronous Coupling of Task-Based Scientific Workflows,”** In *The 2nd International Workshop on Extreme Scale Programming Models and Middleware(ESPM2'16) in conjunction with The International Conference on High Performance Computing, Networking, Storage and Analysis*, Utah, USA, Note: *Best paper award*, Nov, 2016.
 53. [Tan2016a] Houjun Tang, Suren Byna, Steven Harenberg, Xiaocheng Zou, Wenzhao Zhang, Kesheng Wu, Bin Dong, Oliver Rubel, Kristofer Bouchard, Scott Klasky, Nagiza Samatova. **“Usage Pattern-Driven Dynamic Data Layout Reorganization,”** In *16th IEEE/ACM International Symposium on Cluster, Cloud and Grid Computing (CCGrid)*, May, 2016.
 54. [Ton2016a] X. Tong, J. Edwards, C. Chen, H. Shen, C. R. Johnson, P. Wong. **“View-Dependent Streamline Deformation and Exploration,”** In *Transactions on Visualization and Computer Graphics*, Vol. 22, No. 7, IEEE, pp. 1788--1801. July, 2016.
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59. [Zha2016b] Yubo Zhang, Kwan-Liu Ma. **“Decoupled Shading for Real-time Heterogeneous Volume Illumination,”** In *Proceedings of EuroVis 2016 (to appear)*, 2016.
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